# Radiation pressure on single atoms: generalization of an exact analytical approach to multilevel atoms 

L. Podlecki, J. Martin, and T. Bastin* (i)<br>Institut de Physique Nucléaire, Atomique et de Spectroscopie, CESAM, University of Liege, Bât. B15, Sart Tilman, Liège 4000, Belgium *Corresponding author: T.Bastin@uliege.be

Received 4 June 2021; revised 2 September 2021; accepted 2 September 2021; posted 3 September 2021 (Doc. ID 433090); published 6 October 2021


#### Abstract

In a recent work, we provided a standardized and exact analytical formalism for computing in the semiclassical and asymptotic regime, the radiation force experienced by a two-level atom interacting with any number of plane waves with arbitrary intensities, frequencies, phases, and propagation directions [J. Opt. Soc. Am. B 35, 127 (2018)]. Here, we extend this treatment to the multilevel atom case, where degeneracy of the atomic levels is considered and polarization of light enters into play. A matrix formalism is developed to this aim. © 2021 Optical Society of America


https://doi.org/10.1364/JOSAB. 433090

## 1. INTRODUCTION

The mechanical action of laser light on atoms led to a great number of spectacular experiments and achievements in atomic physics during the past decades (see, e.g., Refs. [1-8]). In the semiclassical regime, where the atomic motion is treated classically, the resonant laser radiation produces a mechanical force on the atomic center of mass. Recently, we provided a standardized exact analytical treatment of the mechanical action induced by an arbitrary set of plane waves on a two-level atom [9]. In particular, we showed that the light force always reaches a periodic regime shortly after establishment of the interaction, and we provided an exact yet simple expression of all related Fourier components of the force in this regime. The mean net force $\mathbf{F}$ has been shown to be expressible in all cases (coherent and incoherent) in the form $\mathbf{F}=\sum_{j=1}^{N} \mathbf{F}_{j}$, with

$$
\begin{equation*}
\mathbf{F}_{j}=\frac{\Gamma}{2} \frac{s_{j}}{1+s} \hbar \mathbf{k}_{j} \tag{1}
\end{equation*}
$$

the force exerted by the $j$ th plane wave in presence of all other waves. Here, $N$ is the number of plane waves lightening the atom, $\Gamma$ is the spontaneous de-excitation rate of the upper level of the transition, $\hbar \mathbf{k}_{j}$ is the $j$ th plane wave photon momentum, and $s=\sum_{j} s_{j}$, with $s_{j}$ a generalized saturation parameter

$$
\begin{equation*}
s_{j}=\operatorname{Re}\left[\frac{\Omega_{j}}{\Gamma / 2-i \delta_{j}} \sum_{l=1}^{N} \frac{\Omega_{l}^{*}}{\Gamma} q_{m_{l j}}\right], \tag{2}
\end{equation*}
$$

where $\Omega_{j}$ and $\delta_{j}$ are the Rabi frequency and the detuning of plane wave $j$, and $q_{m_{l j}}$ are complex numbers obtained from the solution of an infinite system of equations [9]. In the
low-intensity and incoherent regime, we showed that Eq. (2) simplifies to the standard expression of the saturation parameter, i.e.,

$$
\begin{equation*}
s_{j}=\frac{\left|\Omega_{j}\right|^{2} / 2}{\Gamma^{2} / 4+\delta_{j}^{2}} \tag{3}
\end{equation*}
$$

One then might naturally bring up the question of how this formalism extends to the multilevel atom case, where Zeeman sublevels and arbitrary polarization of light are considered. In this case, a closed form of the mean net force $\mathbf{F}$ is only known in specific situations. For instance, for an atom with degenerate ground and excited states of angular momenta $J_{g}$ and $J_{e}$, respectively, the stationary force exerted by a linearly polarized plane wave is either 0 (if $\Delta J \equiv J_{e}-J_{g}=-1$, or $\Delta J=0$ with integer $J_{g}$ ) or reads

$$
\begin{equation*}
\mathbf{F}=\frac{\Gamma}{2} \frac{s}{b+s} \hbar \mathbf{k}, \tag{4}
\end{equation*}
$$

with $\hbar \mathbf{k}$ the plane wave photon momentum, $s$ the standard saturation parameter [Eq. (3)], and $b$ a parameter depending on $J_{g}$ and $J_{e}$ [10]. Other specific cases have also been studied in the lin $\perp$ lin and $\sigma^{+}-\sigma^{-}$configurations [11-14]. However, no exact analytical extension of Eq. (4) is known for general atomic and laser configurations. In practice, purely numerical approaches are enforced in this case (see, e.g., Refs. [15-23]).

Here, we extend the formalism developed in Ref. [9] to the multilevel atom case, and we show that an exact analytical expression of the mechanical force exerted by a set of plane waves with arbitrary intrinsic properties (intensity, phase, frequency, polarization, and propagation direction) can be similarly obtained after a transient regime. A matrix formalism
is developed to this aim. The paper is organized as follows. In Section 2, the generalized optical Bloch equation (OBE) formalism is developed, and we extract the sought exact expression of the radiation pressure force in the most general configuration. In Section 3, specific regimes where interesting simplifications occur are investigated, and we draw conclusions in Section 4. Finally, two appendices close this paper, where we detail the effect of a reference frame rotation on the OBEs (Appendix A) and explicit values of specific matrices are given (Appendix B).

## 2. MODEL AND RADIATION PRESSURE FORCE

## A. Hamiltonian and Master Equation

We consider a single atom with two degenerate levels of energy $E_{e} \equiv \hbar \omega_{e}$ and $E_{g} \equiv \hbar \omega_{g}\left(E_{e}>E_{g}\right)$, and of total angular momenta $J_{e}$ and $J_{g}$, respectively. The Zeeman sublevels are denoted $\left|J_{e}, m_{e}\right\rangle$ and $\left|J_{g}, m_{g}\right\rangle$. We consider an electric dipole transition $\left(\Delta J \equiv J_{e}-J_{g} \in\{0, \pm 1\}\right)$ with angular frequency $\omega_{e}-\omega_{g} \equiv \omega_{e g}$. The atom interacts with a classical electromagnetic field $\mathbf{E}(\mathbf{r}, t)$, resulting from the superposition of $N$ arbitrary plane waves, $\mathbf{E}(\mathbf{r}, t)=\sum_{j=1}^{N} \mathbf{E}_{j}(\mathbf{r}, t)$, with $\mathbf{E}_{j}(\mathbf{r}, t)=\left(\mathbf{E}_{j} / 2\right) e^{i\left(\omega_{j} t-\mathbf{k}_{j} \cdot \mathbf{r}+\varphi_{j}\right)}+$ c.c. Here, $\omega_{j}, \mathbf{k}_{j}$, and $\varphi_{j}$ are the angular frequency, the wave vector, and the phase of the $j$ th plane wave, respectively, and $\mathbf{E}_{j} \equiv E_{j} \boldsymbol{\epsilon}_{j}$, with $E_{j}>0$ and $\boldsymbol{\epsilon}_{j}=\sum_{q} \epsilon_{j, q} \mathbf{e}^{q}$ the normalized polarization vector of the corresponding wave written in the upper-index spherical basis $\left\{\mathbf{e}^{q}, q=0, \pm 1\right\}$ [24]. Nonzero $\epsilon_{j, 0}$ and $\epsilon_{j, \pm 1}$ components correspond to so-called $\pi$ and $\sigma^{ \pm}$polarization components of radiation, respectively. Accordingly, the vectors $\mathbf{e}^{0}, \mathbf{e}^{ \pm 1}$ are also denoted by $\boldsymbol{\pi}, \boldsymbol{\sigma}^{ \pm}$, respectively. As in our analysis of the twolevel case [9], the quasi-resonance condition is fulfilled for each plane wave $\left(\left|\delta_{j}\right| \ll \omega_{e g}, \forall j\right.$, where $\delta_{j}=\omega_{j}-\omega_{e g}$ is the detuning). We also define a weighted mean frequency $\bar{\omega}=\sum_{j} \kappa_{j} \omega_{j}$ of the plane waves together with a weighted mean detuning $\bar{\delta}=\sum_{j} \kappa_{j} \delta_{j}=\bar{\omega}-\omega_{e g}$, with $\left\{\kappa_{j}\right\}$ an a priori arbitrary set of weighting factors $\left(\kappa_{j} \geq 0\right.$ and $\left.\sum_{j} \kappa_{j}=1\right)$.

The time evolution of the atomic density operator $\hat{\rho}$ is governed by the standard master equation [25]

$$
\begin{equation*}
\frac{d}{d t} \hat{\rho}(t)=\frac{1}{i \hbar}[\hat{H}(t), \hat{\rho}(t)]+\mathcal{D}(\hat{\rho}(t)) \tag{5}
\end{equation*}
$$

in which $\hat{H}(t)=\hbar \omega_{e} \hat{P}_{e}+\hbar \omega_{g} \hat{P}_{g}-\hat{\mathbf{D}} \cdot \mathbf{E}(\mathbf{r}, t)$ and

$$
\begin{equation*}
\mathcal{D}(\hat{\rho})=-(\Gamma / 2)\left(\hat{P}_{e} \hat{\rho}+\hat{\rho} \hat{P}_{e}\right)+\Gamma \sum_{q}\left(\mathrm{e}^{q^{*}} \cdot \hat{\mathbf{S}}^{-}\right) \hat{\rho}\left(\mathrm{e}^{q} \cdot \hat{\mathbf{S}}^{+}\right) \tag{6}
\end{equation*}
$$

Here, $\hat{P}_{k} \equiv \sum_{m_{k}}\left|J_{k}, m_{k}\right\rangle\left\langle J_{k}, m_{k}\right| \quad(k=e, g), \hat{\mathbf{D}}$ is the atomic electric dipole operator, $\mathbf{r}$ is the atom position in the electric field, and the $\hat{\mathbf{S}}^{ \pm}$operators are defined according to $\mathbf{e}^{q} \cdot \hat{\mathbf{S}}^{+}\left|J_{g}, m_{g}\right\rangle=C_{m_{g}}^{(q)}\left|J_{e}, m_{g}+q\right\rangle, \mathbf{e}^{q} \cdot \hat{\mathbf{S}}^{+}\left|J_{e}, m_{e}\right\rangle=0$, and $\mathbf{e}^{q *} \cdot \hat{\mathbf{S}}^{-}=\left(\mathbf{e}^{q} \cdot \hat{\mathbf{S}}^{+}\right)^{\dagger}$, with

$$
\begin{equation*}
\mathcal{C}_{m}^{(q)} \equiv\left\langle J_{g}, m ; 1, q \mid J_{e}, m+q\right\rangle \tag{7}
\end{equation*}
$$

where $\left\langle j_{1}, m_{1} ; j_{2}, m_{2} \mid j, m\right\rangle$ is the Clebsch-Gordan coefficient corresponding to the coupling of $\left|j_{1}, m_{1}\right\rangle$ and $\left|j_{2}, m_{2}\right\rangle$ into $|j, m\rangle$.

## B. Optical Bloch Equations

All matrix elements $\rho_{\left(J_{k}, m_{k}\right),\left(J_{l}, m_{l}\right)} \equiv\left\langle J_{k}, m_{k}\right| \hat{\rho}\left|J_{l}, m_{l}\right\rangle(k, l=$ $e, g)$ are dependent variables due to hermiticity and unit trace of $\hat{\rho}$. We consider here the column vector of real and independent variables $\mathbf{x}=\left(\mathbf{x}_{o}^{T}, \mathbf{x}_{\xi}^{T}\right)^{T}$, with $\mathbf{x}_{o}$ a column vector of optical coherences and $\mathbf{x}_{\xi} \equiv\left(\mathbf{x}_{p}^{T}, \mathbf{x}_{Z}^{T}\right)^{T}$, where $\mathbf{x}_{p}$ is a column vector of populations and $\mathbf{x}_{Z}$ a column vector of Zeeman coherences. We defined

$$
\mathbf{x}_{o}=\left(\begin{array}{c}
\mathbf{x}_{o}^{\left(-\left(J_{e}+J_{g}\right)\right)}  \tag{8}\\
\vdots \\
\mathbf{x}_{o}^{\left(J_{e}+J_{g}\right)}
\end{array}\right), \quad \text { with } \quad \mathbf{x}_{o}^{(\Delta m)}=\left(\begin{array}{c}
u_{o m}^{(\Delta m)} \\
v_{o, m_{-}^{(\Delta m)}}^{(\Delta m)} \\
o, m_{-}^{(\Delta m)} \\
\vdots \\
u_{o m)}^{(\Delta m)} \\
v_{o m m}^{(\Delta m)} \\
o, m_{+}^{(\Delta m)}
\end{array}\right) \text {, }
$$

where $\quad u_{o, m}^{(\Delta m)} \equiv \operatorname{Re}\left(\rho_{\left(J_{g}, m\right),\left(J_{e}, m+\Delta m\right)} e^{-i \bar{\omega} t}\right) \quad$ and $\quad v_{o, m}^{(\Delta m)} \equiv$ $\operatorname{Im}\left(\rho_{\left(J_{g}, m\right),\left(J_{e}, m+\Delta m\right)} e^{-i \bar{\omega} t}\right)$, with $\quad m=m_{-}^{(\Delta m)}, \ldots, m_{+}^{(\Delta m)}$, $m_{ \pm}^{(\Delta m)}= \pm \min \left(J_{g}, J_{g}+\Delta J \mp \Delta m\right), \quad$ and $\quad \Delta m=$ $-\left(J_{e}+J_{g}\right), \ldots, J_{e}+J_{g}$.

We defined $\mathbf{x}_{p} \equiv\left(\mathbf{x}_{p_{e}}^{T}, \mathbf{x}_{p_{g}}^{T}\right)^{T}$, with $(k=e, g)$

$$
\mathbf{x}_{p k}=\left(\begin{array}{c}
w_{k,-J_{k}+\delta_{k, g}}  \tag{9}\\
\vdots \\
w_{k, J_{k}}
\end{array}\right)
$$

where $\quad w_{k, m_{k}}=\rho_{\left(J_{k}, m_{k}\right),\left(J_{k}, m_{k}\right)}-N_{J}^{-1}$, with $\quad m_{k}=-J_{k}+$ $\delta_{k, g}, \ldots, J_{k}$, and $N_{J} \equiv 2\left(J_{e}+J_{g}+1\right)$.

We finally defined $\mathbf{x}_{Z} \equiv\left(\mathbf{x}_{Z_{e}}^{T}, \mathbf{x}_{Z_{g}}^{T}\right)^{T}$, with $(k=e, g)$

$$
\mathbf{x}_{Z_{k}}=\left(\begin{array}{c}
\mathbf{x}_{Z_{k}}^{(1)}  \tag{10}\\
\vdots \\
\mathbf{x}_{Z_{k}}^{\left(2 J_{k}\right)}
\end{array}\right), \quad \text { with } \quad \mathbf{x}_{Z_{k}}^{(\Delta m)}=\left(\begin{array}{c}
u_{Z_{k},-J_{k}}^{(\Delta m)} \\
v_{Z_{k},-J_{k}}^{(\Delta m)} \\
\vdots \\
u_{Z_{k}, J J_{k}-\Delta m}^{(\Delta m)} \\
v_{Z_{k}, J_{k}-\Delta m}^{(\Delta m)}
\end{array}\right),
$$

where $\quad u_{Z_{k}, m_{k}}^{(\Delta m)}=\operatorname{Re}\left(\rho_{\left(J_{k}, m_{k}\right),\left(J_{k}, m_{k}+\Delta m\right)}\right) \quad$ and $\quad v_{Z_{k}, m_{k}}^{(\Delta m)}=$ $\operatorname{Im}\left(\rho_{\left(J_{k}, m_{k}\right),\left(J_{k}, m_{k}+\Delta m\right)}\right)$, with $\quad m_{k}=-J_{k}, \ldots, J_{k}-\Delta m$, and $\Delta m=1, \ldots, 2 J_{k}$.

In the standard rotating wave approximation, the time evolution of the independent internal degrees of freedom $\mathbf{x}$ directly results from master Eq. (5) and can be written in the form of generalized optical Bloch equations

$$
\begin{equation*}
\frac{d}{d t} \mathbf{x}(t)=A(t) \mathbf{x}(t)+\mathbf{b} \tag{11}
\end{equation*}
$$

with $A(t)$ and $\mathbf{b}$ a square matrix and a column vector, respectively, as detailed hereafter.

## 1. $A(t)$ Matrix

The $A(t)$ matrix reads

$$
\begin{equation*}
A(t)=-\Gamma A_{0}+\operatorname{Im}\left(\boldsymbol{\Omega}(t) \cdot \mathbf{e}_{C}\right) \tag{12}
\end{equation*}
$$

where $A_{0}$ is a time-independent matrix with scalar entries (independent of any reference frame) detailed hereafter, $\boldsymbol{\Omega}(t)=$ $\sum_{j} \boldsymbol{\Omega}_{j}(t) \equiv \sum_{q} \Omega_{q}(t) \mathbf{e}^{q}, \quad$ with $\quad \boldsymbol{\Omega}_{j}(t)=\Omega_{j} e^{i\left(\omega_{j}-\bar{\omega}\right) t} \boldsymbol{\epsilon}_{j}$, where

$$
\begin{equation*}
\Omega_{j}=-\frac{E_{j} e^{i\left(-\mathbf{k}_{j} \cdot \mathbf{r}+\varphi_{j}\right)}}{\hbar} \frac{\left\langle J_{e}\|\mathbf{D}\| J_{g}\right\rangle^{*}}{\sqrt{2 J_{e}+1}} \tag{13}
\end{equation*}
$$

in which $\left\langle J_{e}\|\mathbf{D}\| J_{g}\right\rangle$ denotes the so-called reduced matrix element associated to $\hat{\mathbf{D}}$, and $\mathbf{e}_{C}$ is the (unnormalized) basis vector of matrices $\mathbf{e}_{C}=\sum_{q} C^{(q)} \mathbf{e}_{q}$, with contravariant components $C^{(q)}$ as described hereafter and where $\mathbf{e}_{q}=\mathbf{e}^{q *}(q=0, \pm 1)$ are the lower-index spherical basis vectors ( $\mathbf{e}_{C}$ is said a basis vector in that it rotates similarly with the spherical basis in case of a basis change, so that $\boldsymbol{\Omega}(t) \cdot \mathbf{e}_{C}=\sum_{q} \Omega_{q}(t) C^{(q)}$ does not define a matrix of scalars; see Appendix A).

The $A_{0}$ matrix reads $A_{0}=\operatorname{diag}\left(A_{o o}, A_{\xi \xi}\right)$, with matrix blocks $A_{o o}=\oplus^{\left(\operatorname{dim} \mathbf{x}_{o}\right) / 2} \Delta(1 / 2)$ and $A_{\xi \xi}=\operatorname{diag}\left(A_{p p}, A_{Z Z}\right)$, where

$$
\Delta(z)=\left(\begin{array}{cc}
z & -\delta / \Gamma  \tag{14}\\
\delta / \Gamma & z
\end{array}\right), \quad \forall z \in \mathbb{C}
$$

and $A_{\zeta \zeta}(\zeta=p, Z)$ are blocks of dimension $\operatorname{dim} \mathbf{x}_{\zeta} \times \operatorname{dim} \mathbf{x}_{\zeta}$, themselves structured into subblocks according to

$$
A_{\zeta \zeta}=\left(\begin{array}{cc}
\mathbb{1}_{\zeta e} & 0  \tag{15}\\
A_{\zeta_{g} \zeta_{e}} & 0_{\zeta g}
\end{array}\right)
$$

with, for any symbol $\alpha, \mathbb{1}_{\alpha}\left[0_{\alpha}\right]$ the identity [zero] matrix of dimension $\operatorname{dim} \mathbf{x}_{\alpha} \times \operatorname{dim} \mathbf{x}_{\alpha}$. The $A_{p_{g} p_{e}}$ subblock is of dimension $\operatorname{dim} \mathbf{x}_{p_{g}} \times \operatorname{dim} \mathbf{x}_{p_{e}}$ and of elements $\left(A_{p_{g} p_{e}}\right)_{m_{g} m_{e}}=-\left(\mathcal{C}_{m_{g}}^{\left(m_{e}-m_{g}\right)}\right)^{2}$, with $m_{k}=-J_{k}+\delta_{k, g}, \ldots, J_{k}$ $(k=e, g)$ [here and throughout the paper, we adopt the convention not to index the matrix elements from $(1,1)$ but with indices directly linked to the magnetic sublevels]. The $A_{Z_{g} Z_{e}}$ subblock is of dimension $\operatorname{dim} \mathbf{x}_{Z_{g}} \times \operatorname{dim} \mathbf{x}_{Z_{e}}$ and is itself structured into vertically and horizontally ordered subsubblocks $A_{Z_{g} Z_{e}}^{\left(\Delta m_{g}, \Delta m_{e}\right)}$ of dimension $\operatorname{dim} \mathbf{x}_{Z_{g}}^{\left(\Delta m_{g}\right)} \times \operatorname{dim} \mathbf{x}_{Z_{e}}^{\left(\Delta m_{e}\right)}$, with respective indices $\Delta m_{g}=1, \ldots, 2 J_{g}$ and $\Delta m_{e}=1, \ldots, 2 J_{e}$. The only a priori nonzero of these subsubblocks are for $\Delta m_{g}=\Delta m_{e} \equiv \Delta m$, of elements $A_{Z_{g} Z_{e}}^{(\Delta m, \Delta m)}=\tilde{A}_{Z_{g} Z_{e}}^{(\Delta m, \Delta m)} \otimes \mathbb{1}_{2}$, with $\quad\left(\tilde{A}_{Z_{g} Z_{e}}^{(\Delta m, \Delta m)}\right)_{m_{g} m_{e}}=-\mathcal{C}_{m_{g}}^{\left(m_{e}-m_{g}\right)} \mathcal{C}_{m_{g}+\Delta m}^{\left(m_{e}-m_{g}\right)}$, where $m_{k}=-J_{k}, \ldots, J_{k}-\Delta m(k=e, g)$.

The $C^{(q)}$ matrices read

$$
C^{(q)}=\left(\begin{array}{cc}
0 & C_{o \xi}^{(q)} \otimes(1,-i)^{T}  \tag{16}\\
C_{\xi o}^{(q)} \otimes(1,-i) & 0
\end{array}\right)
$$

with $\quad C_{o \xi}^{(q)}=\left(C_{o p}^{(q)}, C_{o Z}^{(q)}\right) \quad$ and $\quad C_{\xi o}^{(q)}=\left(C_{p o}^{(q)}{ }^{T}, C_{Z o}^{(q)^{T}}\right)^{T}$, where $\quad C_{o p}^{(q)}=\left(C_{o p_{e}}^{(q)}, C_{o p g}^{(q)}\right), \quad C_{p o}^{(q)}=\left(C_{p_{e} o}^{(q)}{ }^{T}, C_{p_{g} o}^{(q)}\right)^{T}$, $C_{o Z}^{(q)}=\left(C_{o Z_{e}}^{(q)}, C_{o Z_{g}}^{(q)}\right)$, and $C_{Z o}^{(q)}=\left(C_{Z_{e} o}^{(q)^{T}}, C_{Z_{g} o}^{(q)}\right)^{T}$. The $C_{o p k}^{(q)}, C_{p k o}^{(q)}, C_{o Z_{k}}^{(q)}$, and $C_{Z_{k} o}^{(q)}(k=e, g)$ blocks exclusively contain Clebsch-Gordan coefficients and are detailed below. In addition, for $\zeta=\xi, p_{e}, p_{g}, p, Z_{e}, Z_{g}, Z$, the $C_{o \zeta}^{(q)}\left[C_{\zeta o}^{(q)}\right]$ blocks are of dimensions $\left(\operatorname{dim} \mathbf{x}_{o} / 2\right) \times \operatorname{dim} \mathbf{x}_{\zeta}$ $\left[\operatorname{dim} \mathbf{x}_{\zeta} \times\left(\operatorname{dim} \mathbf{x}_{o} / 2\right)\right]$.

In accordance with Eq. (8), the $C_{o p k}^{(q)}$ blocks are structured into vertically ordered subblocks indexed with $\Delta m=-\left(J_{g}+J_{e}\right), \ldots, J_{g}+J_{e} \quad$ and of dimension $\left(\operatorname{dim} \mathbf{x}_{o}^{(\Delta m)} / 2\right) \times \operatorname{dim} \mathbf{x}_{p k}$. The only a priori nonzero of these subblocks is for $\Delta m=q$, and we denote it by $\tilde{C}_{o p_{k}}^{(q)}$. Its elements read $\left(\tilde{C}_{o p_{k}}^{(q)}\right)_{m, m_{k}}=\mathcal{C}_{m}^{(q)}\left(\delta_{m,-J_{g}}+\tilde{n}_{k} \delta_{m_{k}, m+n_{k} q}\right) / 2$, with $n_{k}=\delta_{e, k}$ and $\tilde{n}_{k}=2 n_{k}-1$, where $m=m_{-}^{(q)}, \ldots, m_{+}^{(q)}$ and $m_{k}=-J_{k}+\delta_{k, g}, \ldots, J_{k}$. In a same way, the $C_{p k^{o}}^{(q)}$ blocks are structured into horizontally ordered subblocks indexed with $\Delta m=-\left(J_{g}+J_{e}\right), \ldots, J_{g}+J_{e}$ and of dimensions $\operatorname{dim} \mathbf{x}_{p_{k}} \times\left(\operatorname{dim} \mathbf{x}_{o}^{(\Delta m)} / 2\right)$. Again, the only a priori nonzero of these subblocks is for $\Delta m=q$, and it is denoted by $\tilde{C}_{p k}^{(q)}$. Its elements read $\left(\tilde{C}_{p_{k} o}^{(q)}\right)_{m_{k}, m}=-\tilde{n}_{k} \mathcal{C}_{m}^{(q)} \delta_{m, m_{k}-n_{k} q}$, where $m_{k}=-J_{k}+\delta_{k, g}, \ldots, J_{k}$ and $m=m_{-}^{(q)}, \ldots, m_{+}^{(q)}$.

Finally, $\quad C_{Z_{k} o}^{(q)}=-C_{o Z_{k}}^{(q) T} \quad$ and $\quad C_{o Z_{k}}^{(q)}=\sum_{\epsilon= \pm 1} C_{o Z_{k}, \epsilon}^{(q)} \otimes$ (1, $\epsilon i$ ), where, in accordance with Eqs. (8) and (10), $C_{o Z_{k}, \varepsilon}^{(q)}$ is structured into vertically and horizontally ordered subblocks, with respective indices $\Delta m=-\left(J_{g}+J_{e}\right), \ldots, J_{g}+J_{e}$ and $\Delta m_{k}=1, \ldots, 2 J_{k}$. These subblocks are of dimensions $\left(\operatorname{dim} \mathbf{x}_{o}^{(\Delta m)} / 2\right) \times\left(\operatorname{dim} \mathbf{x}_{Z_{k}}^{\left(\Delta m_{k}\right)} / 2\right)$. The only a priori nonzeros of them are for $\Delta m-\epsilon \Delta m_{k}=q$, and they are denoted by $\tilde{C}_{o Z_{k}, \epsilon}^{(q)\left(\Delta m_{k}\right)}$. Their elements read $\left(\tilde{C}_{o Z_{k}, \epsilon}^{(q)\left(\Delta m_{k}\right)}\right)_{m, m_{k}}=$ $\left(\tilde{n}_{k} / 2\right) \mathcal{C}_{m-\epsilon\left(n_{k}-1\right) \Delta m_{k}}^{(q)} \delta_{m_{k}, m+n_{k} q-(1-\epsilon) \Delta m_{k} / 2}, \quad$ where $m=m_{-}^{(\Delta m)}, \ldots, m_{+}^{(\Delta m)}$ and $m_{k}=-J_{k}, \ldots, J_{k}-\Delta m_{k}$.

## 2. $\boldsymbol{b}$ Column Vector

With the convention of using a $\zeta$ index to denote a dim $\mathbf{x}_{\zeta}$ column vector, the $\mathbf{b}$ column vector reads $\mathbf{b}=-\Gamma N_{J}^{-1}\left(\mathbf{b}_{o}^{T}, \mathbf{b}_{\xi}^{T}\right)^{T}$, with $\mathbf{b}_{o}=0$ and $\mathbf{b}_{\xi}=A_{\xi \xi} \mathbf{u}_{\xi}$. Here, $\mathbf{u}_{\xi}=\left(\mathbf{u}_{p}^{T}, \mathbf{u}_{Z}^{T}\right)^{T}$, with $\mathbf{u}_{Z}=0$ and $\mathbf{u}_{p}=\left(\mathbf{u}_{p_{e}}^{T}, \mathbf{u}_{p_{g}}^{T}\right)^{T}$, where $\mathbf{u}_{p_{g}}=0$, and $\mathbf{u}_{p_{e}}$ is a column vector only composed of 1 .

## C. Periodic Regime

The OBEs [Eq. (11)] cannot be solved analytically and require numerical integration in the most general case. However, within the commensurability assumption (all $\omega_{j}-\bar{\omega}$ commensurable), the $\boldsymbol{\Omega}(t)$ and $A(t)$ quantities are periodic in time with the repetition period $T_{c}=2 \pi / \omega_{c}$, where $\omega_{c}=\left(\operatorname{LCM}\left[\left(\omega_{j}-\bar{\omega}\right)^{-1}, \forall j: \omega_{j} \neq \bar{\omega}\right]\right)^{-1}$, and all $m_{j}=\left(\omega_{j}-\bar{\omega}\right) / \omega_{c}$ numbers are integer numbers. In this case, the OBEs admit in all circumstances a $T_{c}$-periodic solution since $\mathbf{x}(t)$ is bounded [26,27]. This solution is unique if the real parts $\lambda$ of the Floquet exponents are all strictly negative, in which case the system necessarily converges to it (and reaches a so-called periodic regime) from any initial state $\mathbf{x}\left(t_{0}\right)$ after a transient of characteristic time $\left|\lambda_{m}\right|^{-1}$, with $\lambda_{m}$ the greatest $\lambda$ [26]. For twolevel atoms, $-\Gamma \leq \lambda \leq-\Gamma / 2$, and the transient characteristic time remains limited to at most $2 \Gamma^{-1}$ [9]. This is not the case anymore for multilevel atoms where greater damping times can be observed. It might even happen that $\lambda=0$, in which case several $T_{c}$-periodic solutions might exist (the Floquet exponents must be computed numerically, and we only observed $\lambda=0$ in specific configurations with $\Delta J=-1$ ). The case $\lambda>0$
can never happen, since this would correspond to unphysical unbounded $\mathbf{x}(t)$.

Any $T_{c}$-periodic solution $\mathbf{x}(t)$ can be expanded according to

$$
\begin{equation*}
\mathbf{x}(t)=\sum_{n=-\infty}^{+\infty} \mathbf{x}^{(n)} e^{i n \omega_{c} t} \tag{17}
\end{equation*}
$$

with Fourier components $\mathbf{x}^{(n)}$. The variable $\mathbf{x}(t)$ is real, continuous, and differentiable, so that $\mathbf{x}^{(-n)}=\mathbf{x}^{(n)^{*}}$ and $\sum_{n}\left|\mathbf{x}^{(n)}\right|^{2}<\infty$. For $\zeta=o, \xi, p, Z, p_{e}, p_{g}, Z_{e}, Z_{g}$, we denote by $\mathbf{x}_{\zeta}^{(n)}$ the Fourier components related to the periodic variable $\mathbf{x}_{\zeta}(t)$. Inserting Eq. (17) into (11) yields the infinite system of equations
$\mathbf{x}_{o}^{(n)}=A_{o o}^{(n)} \sum_{q, j}\left(\check{C}_{o \xi}^{(q)^{*}} \frac{\Omega_{j, q}^{*}}{\Gamma} \mathbf{x}_{\xi}^{\left(n+m_{j}\right)}-\check{C}_{o \xi}^{(q)} \frac{\Omega_{j, q}}{\Gamma} \mathbf{x}_{\xi}^{\left(n-m_{j}\right)}\right), \quad \forall n$,
with $\quad \Omega_{j, q}=\Omega_{j} \epsilon_{j, q}, \quad A_{o o}^{(n)}=-2 i \Gamma^{2} \tau_{n}^{+} \tau_{n}^{-} \mathbb{1}_{\operatorname{dim} \mathbf{x}_{o} / 2} \otimes$ $\Delta\left(-i n \omega_{c} / \Gamma-1 / 2\right), \quad$ and $\quad \check{C}_{o \xi}^{(q)}=C_{o \xi}^{(q)} \otimes(1,-i)^{T} \quad$ [see Eq. (16)], where we defined $\tau_{n}^{ \pm}=1 /\left[\Gamma+2 i\left(n \omega_{c} \pm \bar{\delta}\right)\right]$, and

$$
\begin{equation*}
\mathbf{x}_{\xi}^{(n)}+\sum_{m \in M_{0}} \mathcal{W}_{\xi \xi}^{(n, m)} \mathbf{x}_{\xi}^{(n+m)}=\mathbf{d}_{\xi} \delta_{n, 0}, \quad \forall n \tag{19}
\end{equation*}
$$

In the latter, $\delta_{n, 0}$ denotes the Kronecker symbol, $M_{0}$ is the set of all distinct nonzero integer numbers $m_{l j} \equiv m_{l}-m_{j}(j, l=1, \ldots, N)$, and we defined $\mathcal{W}_{\xi \xi}^{(n, m)}=$ $\left(A_{\xi \xi}^{(n)}+B_{\xi \xi}^{(n, 0)}\right)^{-1} B_{\xi \xi}^{(n, m)}$ and $\mathbf{d}_{\xi}=-N_{J}^{-1}\left(A_{\xi \xi}+\tilde{s}_{\xi \xi}\right)^{-1} A_{\xi \xi} \mathbf{u}_{\xi}$, where we set $A_{\xi \xi}^{(n)}=A_{\xi \xi}+\left(i n \omega_{c} / \Gamma\right) \mathbb{1}_{\xi}, \quad B_{\xi \xi}^{(n, m)}=$ $\sum_{j, l: m_{l j}=m} \sum_{q, q^{\prime}}\left(\Omega_{j, q} \Omega_{l, q^{\prime}}^{*} / \Gamma\right)\left(\tau_{n-m_{j}}^{-}\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}+\tau_{n+m_{l}}^{+}\left(C_{\xi \xi}\right)_{q}^{q^{\prime *}}\right)$ with $\left(C_{\xi \xi}\right)_{q^{\prime}}^{q} \equiv-C_{\xi o}^{(q)} C_{o \xi}^{\left(q^{\prime}\right) *}$, and $\tilde{s}_{\xi \xi}=\sum_{j} \tilde{s}_{\xi \xi, j}$ with

$$
\begin{equation*}
\tilde{s}_{\xi \xi, j}=\operatorname{Re}\left[\sum_{q, q^{\prime}} \sum_{\substack{l=1 \\ l: m l_{j}=0}}^{N} \frac{\Omega_{j, q} \Omega_{l, q^{\prime}}^{*} / \Gamma}{\Gamma / 2-i \delta_{j}}\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}\right] . \tag{20}
\end{equation*}
$$

We have $\tau_{-n}^{ \pm}=\tau_{n}^{\mp *}, A_{\xi \xi}^{(-n)}=A_{\xi \xi}^{(n) *}, B_{\xi \xi}^{(-n,-m)}=B_{\xi \xi}^{(n, m) *}$, and $\mathcal{W}_{\xi \xi}^{(-n,-m)}=\mathcal{W}_{\xi \xi}^{(n, m) *}[28]$.

If we define $\mathbf{y}=\left(\ldots, \mathbf{x}_{\xi}^{(-1)^{T}}, \mathbf{x}_{\xi}^{(0)^{T}}, \mathbf{x}_{\xi}^{(1)^{T}}, \ldots\right)^{T}$, the infinite column vector of all $\mathbf{x}_{\xi}^{(n)}$ components, as well as

$$
W=\left(\begin{array}{ccccc}
\ddots & \vdots & \vdots & \vdots & .  \tag{21}\\
\ldots & W_{\xi \xi}^{(-1,-1)} & W_{\xi \xi}^{(-1,0)} & W_{\xi \xi}^{(-1,1)} & \ldots \\
\ldots & W_{\xi \xi}^{(0,-1)} & W_{\xi \xi}^{(0,0)} & W_{\xi \xi}^{(0,1)} & \ldots \\
\ldots & W_{\xi \xi}^{(1,-1)} & W_{\xi \xi}^{(1,0)} & W_{\xi \xi}^{(1,1)} & \ldots \\
. & \vdots & \vdots & \vdots & \ddots
\end{array}\right),
$$

the infinite matrix structured into the subblocks $W_{\xi \xi}^{\left(n, n^{\prime}\right)}=$ $\sum_{m \in M_{0}} \mathcal{W}_{\xi \xi}^{(n, m)} \delta_{n^{\prime}, n+m}\left(n, n^{\prime}\right.$ ranging from $-\infty$ to $+\infty$ ), then Eq. (19) yields the complex inhomogeneous infinite system of equations

$$
\begin{equation*}
(I+W) \mathbf{y}=\mathbf{c} \tag{22}
\end{equation*}
$$

with $\mathbf{c}=\left(\ldots, \mathbf{c}_{\xi}^{(-1)^{T}}, \mathbf{c}_{\xi}^{(0)^{T}}, \mathbf{c}_{\xi}^{(1)^{T}}, \ldots\right)^{T}$ the infinite column vector of subblocks $\mathbf{c}_{\xi}^{(n)}=\mathbf{d}_{\xi} \delta_{n, 0}$ ( $n$ ranging from $-\infty$ to $+\infty$ ) and $I$ the infinite identity matrix. We directly have $W_{\xi \xi}^{(n, n)}=0$, $\forall n$. The solution of the system in Eq. (22) necessarily yields $\mathbf{x}_{\xi}^{(0)} \neq 0$; otherwise, all other $\mathbf{x}_{\xi}^{(n)}$ components would solve a homogeneous system of equations and thus vanish, in which case the equation for $n=0$ could not be satisfied. This allows us to define the matrices $Q_{\xi \xi}^{(n)}$ that map the $\mathbf{x}_{\xi}^{(0)}$ vector onto $\mathbf{x}_{\xi}^{(n)}$, $\forall n: Q_{\xi \xi}^{(n)} \mathbf{x}_{\xi}^{(0)}=\mathbf{x}_{\xi}^{(n)}$. The $Q_{\xi \xi}^{(n)}$ matrices are a priori not unique [29]. Inserting $\mathbf{x}_{\xi}^{(n)}=Q_{\xi \xi}^{(n)} \mathbf{x}_{\xi}^{(0)}$ into Eq. (19) for $n=0$ yields

$$
\begin{equation*}
\mathbf{x}_{\xi}^{(0)}=-\frac{1}{N_{J}} \frac{A_{\xi \xi}}{A_{\xi \xi}+s_{\xi \xi}} \mathbf{u}_{\xi}, \tag{23}
\end{equation*}
$$

where $\frac{A_{\xi \xi}}{A_{\xi \xi}+s_{\xi \xi}} \equiv\left(A_{\xi \xi}+s_{\xi \xi}\right)^{-1} A_{\xi \xi}$ and $s_{\xi \xi}=\sum_{j} s_{\xi \xi, j}$, with

$$
\begin{equation*}
s_{\xi \xi, j}=\operatorname{Re}\left[\sum_{q, q^{\prime}} \sum_{l=1}^{N} \frac{\Omega_{j, q} \Omega_{l, q^{\prime}}^{*} / \Gamma}{\Gamma / 2-i \delta_{j}}\left(C_{\xi \xi}\right)_{q^{\prime}}^{q} Q_{\xi \xi}^{\left(m_{l j}\right)}\right] . \tag{24}
\end{equation*}
$$

Equation (24) is the generalization of Eq. (15) of Ref. [9] to the degenerate two-level atom case.

## D. General and Exact Expression of the Radiation Force

Proceeding along the same lines as in Ref. [9], the total mean power absorbed from all plane waves and the mean net force exerted on the atom can be expressed as $P(t)=\sum_{j} P_{j}(t)$ and $\mathbf{F}(t)=\sum_{j} \mathbf{F}_{j}(t)$, respectively, with $P_{j}(t)=R_{j}(t) \hbar \bar{\omega}$ and $\mathbf{F}_{j}(t)=R_{j}(t) \hbar \mathbf{k}_{j}$, where

$$
\begin{equation*}
R_{j}(t)=\operatorname{Im}\left[\boldsymbol{\Omega}_{j}(t) \cdot \boldsymbol{\chi}_{o}(t)\right], \tag{25}
\end{equation*}
$$

with $\chi_{o}(t) \equiv \sum_{q} \chi_{o}^{(q)}(t) \mathbf{e}_{q}$ the three-dimensional vector of contravariant components

$$
\begin{equation*}
\chi_{o}^{(q)}(t)=-\sum_{m=m_{-}^{(q)}}^{m_{+}^{(q)}} \mathcal{C}_{m}^{(q)}\left(u_{o, m}^{(q)}(t)-i v_{o, m}^{(q)}(t)\right) \tag{26}
\end{equation*}
$$

The vector $\chi_{o}(t)$ is a true polar vector (see Appendix A), so that obviously $\boldsymbol{\Omega}_{j}(t) \cdot \boldsymbol{\chi}_{o}(t)$ is a scalar quantity. As a reminder [9], $R_{j}(t)$ merely yields in the quasi-resonance condition, the mean photon absorption rate, $\langle d N / d t\rangle_{j}(t)$, induced by plane wave $j$.

In a periodic regime, $R_{j}(t)$ can be expanded according to $\sum_{n=-\infty}^{+\infty} R_{j}^{(n)} e^{i n \omega_{c} t}$, with Fourier components $R_{j}^{(n)}$. When this regime is unique, these components are obtained by inserting Eq. (18) into Eq. (25) and considering $Q_{\xi \xi}^{(n)} \mathbf{x}_{\xi}^{(0)}=\mathbf{x}_{\xi}^{(n)}$, along with $\mathbf{x}_{\xi}^{(0)}$ as given by Eq. (23). This yields

$$
\begin{equation*}
R_{j}^{(n)}=\frac{\Gamma}{N_{J}} \mathbf{u}_{\xi}^{T} s_{\xi \xi, j}^{(n)} \frac{A_{\xi \xi}}{A_{\xi \xi}+s_{\xi \xi}} \mathbf{u}_{\xi}=-\Gamma \mathbf{u}_{\xi}^{T} s_{\xi \xi, j}^{(n)} \mathbf{x}_{\xi}^{(0)}, \tag{27}
\end{equation*}
$$

where $s_{\xi \xi, j}^{(n)}=\left(\sigma_{\xi \xi, j}^{(n)}+\sigma_{\xi \xi, j}^{(-n)^{*}}\right) / 2$, with

$$
\begin{equation*}
\sigma_{\xi \xi, j}^{(n)}=\sum_{q, q^{\prime}} \sum_{l=1}^{N} \frac{\Omega_{j, q} \Omega_{l, q^{\prime}}^{*} / \Gamma}{\Gamma / 2+i\left(n \omega_{c}-\delta_{j}\right)}\left(C_{\xi \xi}\right)_{q^{\prime}}^{q} Q_{\xi \xi}^{\left(n+m m_{j j}\right)} . \tag{28}
\end{equation*}
$$

In particular, observing that $s_{\xi \xi, j}^{(0)}=s_{\xi \xi, j}$ [Eq. (24)], the temporal mean value $\bar{R}_{j} \equiv R_{j}^{(0)}$ of $R_{j}(t)$ in the unique periodic regime reads

$$
\begin{equation*}
\bar{R}_{j}=\frac{\Gamma}{N_{J}} \mathbf{u}_{\xi}^{T} s_{\xi \xi, j} \frac{A_{\xi \xi}}{A_{\xi \xi}+s_{\xi \xi}} \mathbf{u}_{\xi}, \tag{29}
\end{equation*}
$$

and the corresponding mean force similarly reads

$$
\begin{equation*}
\overline{\mathbf{F}}_{j}=\frac{\Gamma}{N_{J}}\left(\mathbf{u}_{\xi}^{T} s_{\xi \xi, j} \frac{A_{\xi \xi}}{A_{\xi \xi}+s_{\xi \xi}} \mathbf{u}_{\xi}\right) \hbar \mathbf{k}_{j} . \tag{30}
\end{equation*}
$$

Equation (30) is a natural extension of Eq. (19) of Ref. [9]. Interestingly, the two-level atom case is also covered within the present formalism. To this aim, it is enough to consider $J_{g}=J_{e}=0$ and to open artificially the forbidden 0-0 transition by forcing $\mathcal{C}_{0}^{(0)}$ to 1 . All equations above then merely simplify to the two-level atom formalism of Ref. [9].

To illustrate our formalism, we show how the stimulated bichromatic force in a standard four traveling-wave configuration [30] compares between the two-level [9] and multilevel atom cases for several atomic structures. Light with pure $\pi$ polarization ( $\boldsymbol{\epsilon}_{j}=\boldsymbol{\pi}, \forall j$ ) was considered for the comparison. We show in Fig. 1 the value of the resulting bichromatic force (averaged over the $2 \pi$ range of the spatially varying relative phase between the opposite waves) acting in the direction of the phased wave on a moving atom as a function of its velocity $v$ for $\Delta J=1$ with $J_{g}=1 / 2,1, \ldots, 4$. Figure 1 shows that the $\pi$ polarization case yields poorer results than the ideal two-level atom case.

## 3. SPECIFIC REGIMES

The general expression of the mean photon absorption rate [Eq. (29)] can be interestingly simplified in several specific regimes. We investigate some emblematic cases in the next subsections.

## A. Low-Intensity Regime

We define the low-intensity regime as the regime where $\sum_{j}\left|\Omega_{j}\right| / \Gamma \ll 1$ (this requires that the sum of field intensities be much smaller than the transition saturation intensity


Fig. 1. Stimulated bichromatic force $F$ as a function of the atomic velocity $v$ computed via our formalism for a detuning $\delta=10 \Gamma$, a Rabi frequency of $\sqrt{3 / 2} \delta$, a phase shift of $\pi / 2$ for one wave, $\boldsymbol{\epsilon}_{j}=\boldsymbol{\pi}, \forall j$, and $J_{g}=1 / 2,1, \ldots, 4$ with $\Delta J=1$.
[31]). In this regime, and provided the matrices $\mathcal{W}_{\xi \xi}^{(n, m)}$ remain small enough [32], we have $s_{\xi \xi, j} \simeq \tilde{s}_{\xi \xi, j}$ and $\bar{R}_{j}$ can be directly computed without solving the infinite system in Eq. (22) [33]. With all distinct frequencies, this implies [see Eq. (20)]

$$
\begin{equation*}
s_{\xi \xi, j} \simeq \operatorname{Re}\left[\sum_{q, q^{\prime}}\left(\frac{\Omega_{j, q} \Omega_{j, q^{\prime}}^{*} / \Gamma}{\Gamma / 2-i \delta_{j}}\right)\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}\right] . \tag{31}
\end{equation*}
$$

Otherwise, coherent effects can be observed. The only incoherent contribution is obtained with an averaging $\langle\cdot\rangle_{\varphi}$ over all phase differences. For $N=2$ with $\boldsymbol{\epsilon}_{1}=\boldsymbol{\sigma}^{+}$and $\boldsymbol{\epsilon}_{2}=\boldsymbol{\sigma}^{-}$, we get in particular $\bar{R}_{j}^{\mathrm{inc}} \equiv\left\langle\bar{R}_{j}\right\rangle_{\varphi} \simeq$ $\Gamma N_{J}^{-1} \mathbf{u}_{\xi}^{T}\left\langle\tilde{s}_{\xi \xi, j}\right\rangle_{\varphi}\left(A_{\xi \xi}+\sum_{i}\left\langle\tilde{s}_{\xi \xi, i}\right\rangle_{\varphi}\right)^{-1} A_{\xi \xi} \mathbf{u}_{\xi}$. For such polarization vectors, we further have $\left\langle\tilde{s}_{\xi \xi, j}\right\rangle_{\varphi}=$ $\operatorname{Re}\left[\left(\left|\Omega_{j}\right|^{2} / \Gamma\right) /\left(\Gamma / 2-i \delta_{j}\right)\left(C_{\xi \xi}\right)_{q_{j}}^{q_{j}}\right]$, where $q_{1}=1=-q_{2}$. Since $\left(C_{\xi \xi}\right)_{q}^{q}$ has the block-diagonal structure (see Appendix B)

$$
\left(C_{\xi \xi}\right)_{q}^{q}=\left(\begin{array}{cc}
\left(C_{p p}\right)_{q}^{q} & 0  \tag{32}\\
0 & \left(C_{Z Z}\right)_{q}^{q}
\end{array}\right)
$$

with $\left(C_{\zeta \zeta}\right)_{q}^{q}=-C_{\zeta o}^{(q)} C_{o \zeta}^{(q)}{ }^{*}(\zeta=p, Z)$, it follows that $\left\langle\tilde{s}_{\xi \xi, j}\right\rangle_{\varphi}$ has the same block-diagonal structure. In addition, $A_{\xi \xi}$ behaves similarly, and since all $\left(C_{p p}\right)_{q}^{q}$ matrix elements are real numbers, $\bar{R}_{j}^{\text {inc }}$ simplifies to $\bar{R}_{j}^{\mathrm{inc}} \simeq \Gamma N_{J}^{-1} s_{j} f_{j}\left(s_{1}, s_{2}\right)$, with $\quad s_{j} \equiv\left(\left|\Omega_{j}\right|^{2} / 2\right) /\left(\Gamma^{2} / 4+\delta_{j}^{2}\right) \quad$ and $\quad f_{j}\left(s_{1}, s_{2}\right)=$ $\mathbf{u}_{p}^{T}\left(C_{p p}\right)_{q_{j}}^{q_{j}}\left(A_{p p}+\sum_{i=1}^{2} s_{i}\left(C_{p p}\right)_{q_{i}}^{q_{i}}\right)^{-1} A_{p p} \mathbf{u}_{p}$.

## B. Plane Waves with the Same Frequency

In this case, any periodic regime is a strict stationary regime ( $R_{j}^{(n)}=0, \forall n \neq 0$ ), and $s_{\xi \xi, j}$ [see Eq. (24)] simplifies to $\operatorname{Re}\left[\sum_{q, q^{\prime}}\left(s_{j}\right)_{q}^{q^{\prime}}\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}\right]$, where $\left(s_{j}\right)_{q}^{q^{\prime}}$ is the second-order tensor $\left(\Omega_{j, q} \Omega_{q^{\prime}}^{*} / \Gamma\right) /(\Gamma / 2-i \delta)$, with $\delta \equiv \delta_{j}$, $\forall j$. Here, $\Omega_{q}$ is independent of time and merely identifies to $\sum_{j} \Omega_{j, q}$.

For $N=1$, the index $j=1$ can be omitted, and we get $\underline{s}_{q}^{q^{\prime}}=s(1+2 i \delta / \Gamma) \epsilon_{q} \epsilon_{q^{\prime}}^{*} \quad$ with $\quad s=\left(|\Omega|^{2} / 2\right) /\left(\Gamma^{2} / 4+\delta^{2}\right)$ and $\bar{R}=\Gamma N_{J}^{-1} \mathbf{u}_{\xi}^{T} f_{\xi \xi}\left(A_{\xi \xi}+f_{\xi \xi}\right)^{-1} A_{\xi \xi} \mathbf{u}_{\xi}$, where we set $f_{\xi \xi} \equiv \operatorname{Re}\left[\sum_{q, q^{\prime}} \underline{q}_{q}^{q^{\prime}}\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}\right]$. For a given atomic structure and in contrast to $A_{\xi \xi}$ and $\mathbf{u}_{\xi}$, the $f_{\xi \xi}$ matrix depends on $s, \boldsymbol{\epsilon}$, and $\delta$ (at constant $s$ ): $f_{\xi \xi} \equiv f_{\xi \xi}(s, \boldsymbol{\epsilon}, \delta)$. We can thus expect the same for $\bar{R}$ that is dependent on $f_{\xi \xi}: \bar{R} \equiv \bar{R}(s, \boldsymbol{\epsilon}, \delta)$. However, this is not exactly the case: at constant $s, \bar{R}$ does not depend on $\delta$. We have [34]

$$
\begin{equation*}
\bar{R}(s, \boldsymbol{\epsilon}, \delta)=\bar{R}(s, \boldsymbol{\epsilon}, 0) \tag{33}
\end{equation*}
$$

## C. Plane Waves with the Same Pure Polarization

If all plane waves have the same pure polarization $q\left(\boldsymbol{\epsilon}_{j}=\mathbf{e}^{q}\right.$, $\forall j$ ), then each $\mathcal{W}_{\xi \xi}^{(n, m)}$ matrix is block-diagonal with blocks $\mathcal{W}_{p p}^{(n, m)}$ and $\mathcal{W}_{Z Z}^{(n, m)}$ of dimensions $\operatorname{dim} \mathbf{x}_{p} \times \operatorname{dim} \mathbf{x}_{p}$ and $\operatorname{dim} \mathbf{x}_{Z} \times \operatorname{dim} \mathbf{x}_{Z}$, respectively, because so are the $\left(C_{\xi \xi}\right)_{q}^{q}$ matrices, with corresponding blocks $\left(C_{p p}\right)_{q}^{q}$ and $\left(C_{Z Z}\right)_{q}^{q}$. In addition, the $\operatorname{dim} \mathbf{x}_{Z}$ last components of the $\mathbf{d}_{\xi}$ vector vanish,
and its $\operatorname{dim} \mathbf{x}_{p}$ first components are denoted hereafter by $\mathbf{d}_{p}$. Equation (19) then yields the decoupled system

$$
\left\{\begin{array}{l}
\mathbf{x}_{p}^{(n)}+\sum_{m \in M_{0}} \mathcal{W}_{p p}^{(n, m)} \mathbf{x}_{p}^{(n+m)}=\mathbf{d}_{p} \delta_{n, 0}  \tag{34}\\
\mathbf{x}_{Z}^{(n)}+\sum_{m \in M_{0}} \mathcal{W}_{Z Z}^{(n, m)} \mathbf{x}_{Z}^{(n+m)}=0
\end{array}\right.
$$

which can be solved separately for the $\mathbf{x}_{p}^{(n)}$ and $\mathbf{x}_{Z}^{(n)}$ Fourier components. The $\mathbf{x}_{Z}^{(n)}$ components satisfy a homogeneous system with trivial solution $\mathbf{x}_{Z}^{(n)}=0, \forall n$. This implies that the $\operatorname{dim} \mathbf{x}_{Z}$ last components of $\mathbf{z}_{\xi}^{(n)}$ are zero, and then the $Q_{\xi \xi}^{(n)}$ matrix is block-diagonal with blocks $Q_{p p}^{(n)}$ and $Q_{Z Z}^{(n)}$ of dimensions $\operatorname{dim} \mathbf{x}_{p} \times \operatorname{dim} \mathbf{x}_{p}$ and $\operatorname{dim} \mathbf{x}_{Z} \times \operatorname{dim} \mathbf{x}_{Z}$, respectively. As a consequence, $\sigma_{\xi \xi, j}^{(n)}$ are in turn block-diagonal with the same structure, $\forall n$, and so are $s_{\xi \xi, j}^{(n)}$ with corresponding blocks $s_{p p, j}^{(n)}$ and $s_{Z Z, j}^{(n)}$. In particular, Eqs. (23) and (27) yield $\mathbf{x}_{p}^{(0)}=-N_{J}^{-1}\left(A_{p p}+s_{p p}\right)^{-1} A_{p p} \mathbf{u}_{p}$ and $R_{j}^{(n)}=\Gamma N_{J}^{-1}$ $\mathbf{u}_{p}^{T} s_{p p, j}^{(n)}\left(A_{p p}+s_{p p}\right)^{-1} A_{p p} \mathbf{u}_{p}$, respectively, with $s_{p p}=\sum_{j} s_{p p, j}$, where $s_{p p, j} \equiv s_{p p, j}^{(0)}$.

In the low-intensity regime and with all distinct frequencies, we get $s_{p p, j} \simeq s_{j}\left(C_{p p}\right)_{q}^{q}$ and $\bar{R}_{j}=$ $\Gamma N_{J}^{-1} s_{j} \mathbf{u}_{p}^{T}\left(C_{p p}\right)_{q}^{q}\left(A_{p p}+s\left(C_{p p}\right)_{q}^{q}\right)^{-1} A_{p p} \mathbf{u}_{p}, \quad$ respectively, with $s=\sum_{j} s_{j}$ and $s_{j}=\left(\left|\Omega_{j}\right|^{2} / 2\right) /\left(\Gamma^{2} / 4+\delta_{j}^{2}\right)$.

## D. Plane Waves with the Same Frequency and Pure Polarization

If all plane waves have the same frequency and the same pure polarization $q, \Omega(t)$ is independent of time with an amplitude $\Omega=\sum_{j} \Omega_{j}$, and $\bar{R}_{j}$ simplifies to

$$
\begin{equation*}
\bar{R}_{j}=\frac{\Gamma}{2} s_{j} \frac{a_{\Delta J, J_{g}, q}}{b_{\Delta J, J_{g}, q}+s} \tag{35}
\end{equation*}
$$

with $s_{j}=\operatorname{Re}\left[\left(\Omega_{j} \Omega^{*} / \Gamma\right) /(\Gamma / 2-i \delta)\right], s=\sum_{j} s_{j}$, and where $\delta \equiv \delta_{j}, \forall j$. For $\Delta J=1$, or $\Delta J=0$ with $q=0$ and half-integer $J_{g}, a_{\Delta J, J_{g}, q}=1$ and

$$
\begin{equation*}
b_{\Delta J, J_{g}, q}=\frac{\operatorname{det}\left[A_{p p,+}^{q}\right]+(-1)^{2 J_{g}} \operatorname{det}\left[A_{p p,-}^{q}\right]}{\operatorname{det}\left[A_{p p,+}^{q}\right]-(-1)^{2 J_{g}} \operatorname{det}\left[A_{p p,-}^{q}\right]} \tag{36}
\end{equation*}
$$

with $A_{p p, \pm}^{q} \equiv A_{p p} \pm\left(C_{p p}\right)_{q}^{q}$. For $\Delta J=0$ with $q \neq 0$ or integer $J_{g}, a_{\Delta J, J_{g}, q}=b_{\Delta J, J_{g}, q}=0$. In particular, we have $b_{1, J_{g}, \pm 1}=1$. For $\Delta J=1$, Eq. (35) yields

$$
\bar{R}_{j}= \begin{cases}\frac{\Gamma}{2} \frac{s_{j}}{1+s} & \text { for } q= \pm 1  \tag{37}\\ \frac{\Gamma}{2} \frac{s_{j}}{b_{1, J_{g}, 0}+s} & \text { for } q=0\end{cases}
$$

For $q= \pm 1$, in the periodic regime, the atom is pumped into the $\left|J_{g}, m_{g}= \pm J_{g}\right\rangle$ state from which it interacts only with the $\left|J_{e}, m_{e}= \pm J_{e}\right\rangle$ state through the radiation action. The atom then exactly behaves as a two-level system. For $q=0$, all populations are nonzero apart from $m_{e}= \pm J_{e}$ and the result is more subtle. For $\Delta J=0$, Eq. (35) yields $\bar{R}_{j}=0$ for $q= \pm 1$ and

$$
\bar{R}_{j}= \begin{cases}0 & \text { if } \mathrm{J}_{g} \text { is integer }  \tag{38}\\ \frac{\Gamma}{2} \frac{s_{j}}{b_{0, J_{g}, 0}+s} & \text { if } \mathrm{J}_{g} \text { is half-integer }\end{cases}
$$



Fig. 2. Values of (a) $b_{1, J_{g}, 0}$ and (b) $b_{0, J_{g}, 0}$ as a function of $J_{g}$.
for $q=0$. For $q= \pm 1$, the atom is pumped into the $\left|J_{g}, m_{g}= \pm J_{g}\right\rangle$ state on which $\sigma^{ \pm}$radiation has no effect. For $q=0$ and integer $J_{g}$, since the Clebsch-Gordan coefficient $\mathcal{C}_{0}^{(0)}$ is zero whatever $J_{g}$, the atom is pumped into the $\left|J_{g}, m_{g}=0\right\rangle$ state from which $\pi$ radiation has no effect. For $q=0$ and half-integer $J_{g}$, all populations are nonzero. We recall that our formalism does not apply for all plane waves with same polarization in the $\Delta J=-1$ case [since $\operatorname{det}\left(A_{\xi \xi}^{(0)}+B_{\xi \xi}^{(0,0)}\right)=0$ ]. Equations (37) and (38) perfectly reproduce the results of Ref. [10] that investigate those specific configurations. We show in Fig. 2 the parameters $b_{1, J_{g}, 0}$ and $b_{0, J_{g}, 0}$ as a function of $J_{g}$.

## E. Two-Frequency Case

For $N$ plane waves with only two distinct frequencies $\omega$ and $\omega^{\prime}$, the system can be tackled in a continued fraction approach as in the two-level atom case [9], though with a matrix formalism. Within the commensurability assumption, we get $n \kappa=n^{\prime} \kappa^{\prime}$, with $n$ and $n^{\prime}$, two positive coprime integers, and $\kappa\left[\kappa^{\prime}\right]$, the cumulative weight $\sum_{j} \kappa_{j}$ of plane waves of frequency $\omega\left[\omega^{\prime}\right]$. This yields $\omega_{c}=\left|\omega-\omega^{\prime}\right| / n_{s}$, with $n_{s}=n+n^{\prime}$, $\omega-\bar{\omega}=m \omega_{c}, \quad \omega^{\prime}-\bar{\omega}=m^{\prime} \omega_{c}$, with $\quad m=\operatorname{sgn}\left(\omega-\omega^{\prime}\right) n$, $m^{\prime}=\operatorname{sgn}\left(\omega^{\prime}-\omega\right) n^{\prime}$, and $M_{0}=\left\{ \pm n_{s}\right\}$. The Fourier components $\mathbf{x}_{\xi}^{(n)}$ that obey the infinite system in Eq. (19) subdivide in two decoupled groups: a first group of components of indices $n=k n_{s}(k \in \mathbb{Z})$ and the group of all remaining ones $\left(n \neq k n_{s}\right)$. The components of the first group get coupled between each other through the system

$$
\begin{equation*}
\mathbf{x}_{\xi}^{(n)}+\mathcal{W}_{\xi \xi}^{\left(n, n_{s}\right)} \mathbf{x}_{\xi}^{\left(n+n_{s}\right)}+\mathcal{W}_{\xi \xi}^{\left(n,-n_{s}\right)} \mathbf{x}_{\xi}^{\left(n-n_{s}\right)}=\mathbf{d}_{\xi} \delta_{n, 0} . \tag{39}
\end{equation*}
$$

The components of the second group satisfy a homogeneous system and merely vanish. Therefore, the only a priori nonzero $Q_{\xi \xi}^{(n)}$ matrices are for the $n$ indices of the first group, and similarly for the $R_{j}^{(n)}$ and $\mathbf{F}_{j}^{(n)}$ Fourier components (as for two-level atoms [9]). As long as one can define the matri$\operatorname{ces} Q_{\xi \xi}^{(n, m)}$ that map $\mathbf{x}_{\xi}^{(n)}$ onto $\mathbf{x}_{\xi}^{(n+m)}, \forall m, n: Q_{\xi \xi}^{(n, m)} \mathbf{x}_{\xi}^{(n)}=$ $\mathbf{x}_{\xi}^{(n+m)}$, Eq. (39) yields, $\forall n=k n_{s} \neq 0, \quad Q_{\xi \xi}^{\left(n-n_{s}, n_{s}\right)}=$ $-\mathcal{W}_{\xi \xi}^{\left(n,-n_{s}\right)} /\left(\mathbb{1}_{\xi}+\mathcal{W}_{\xi \xi}^{\left(n, n_{s}\right)} Q_{\xi \xi}^{\left(n, n_{s}\right)}\right)$, where $A / B \equiv B^{-1} A$. This implies $\quad Q_{\xi \xi}^{\left(n_{s}\right)}=-\mathcal{W}_{\xi \xi}^{\left(n_{s},-n_{s}\right)} /\left[\mathbb{1}_{\xi}+\mathcal{K}_{k=1}^{\infty}\left(P_{\xi \xi, k} / \mathbb{1}_{\xi}\right)\right]$, with $P_{\xi \xi, k}=-\mathcal{W}_{\xi \xi}^{\left(k n_{s}, n_{s}\right)} \mathcal{W}_{\xi \xi}^{\left((k+1) n_{s},-n_{s}\right)} \quad$ and $\quad \mathcal{K}_{k=1}^{\infty}\left(P_{\xi \xi, k} / \mathbb{1}_{\xi}\right) \equiv$ $P_{\xi \xi, 1} /\left(\mathbb{1}_{\xi}+P_{\xi \xi, 2} /\left(\mathbb{1}_{\xi}+P_{\xi \xi, 3} / \ldots\right)\right)$, provided all matrix inverses hold. For $n=k n_{s}$ with $k>1$, Eq. (39) also yields the recurrence relation $Q_{\xi \xi}^{\left((k+1) n_{s}\right)}=-\left(Q_{\xi \xi}^{\left(k n_{s}\right)}+\right.$ $\left.\mathcal{W}_{\xi \xi}^{\left(-k n_{s}, n_{s}\right) *} Q_{\xi \xi}^{\left((k-1) n_{s}\right)}\right) / \mathcal{W}_{\xi \xi}^{\left(k n_{s}, n_{s}\right)}$ that allows for the
calculation of the remaining $Q_{\xi \xi}^{\left(k n_{s}\right)}$ along with all nonzero Fourier components $R_{j}^{\left(k n_{s}\right)}$ and $\mathbf{F}_{j}^{\left(k n_{s}\right)}$.

## 4. CONCLUSION

In conclusion, we have extended the formalism of Ref. [9] to the multilevel atom case, where Zeeman sublevels and arbitrary light polarization are taken into account. In that context, we have provided a general standardized and exact analytical formalism for directly computing in the asymptotic regime and within the usual rotating wave approximation the mechanical action experienced by a single multilevel atom lightened simultaneously by an arbitrary set of plane waves. By use of a Fourier expansion treatment, we provided an exact analytical expression of all Fourier components $\mathbf{F}_{j}^{(n)}$ describing the light forces in the periodic regime if unique. In particular, we generalized the expression of the steady mean net force from Eq. (1) to Eq. (30), involving matrix quantities whose dimensions depend on the atomic structure. In addition, we highlighted some simplifications that hold in specific regimes. The computation of the Fourier components related to the light forces relies on the solution of an algebraic system of equations and does not require numerical integration of the OBEs with time.

## APPENDIX A: REFERENCE FRAME ROTATION

The states $\left|J_{g}, m_{g}\right\rangle$ and $\left|J_{e}, m_{e}\right\rangle$ are common eigenstates of $\hat{\mathbf{J}}^{2}$ and $\hat{J}_{z}$, with $\hat{\mathbf{J}}$ the total angular momentum and $\hat{J}_{z}$ its $z$ component in the considered reference frame $S$. If $S$ is rotated according to Euler angles $\alpha, \beta, \gamma$ to a new configuration $\underline{S}$, the component $\hat{J}_{z}$ transforms to $\hat{L}_{z}=\hat{R}(\alpha, \beta, \gamma) \hat{J_{z}} \hat{R}(\alpha, \beta, \gamma)^{\dagger}$, with the rotation operator $\hat{R}(\alpha, \beta, \gamma)=e^{-i \alpha \hat{J}_{z} / \hbar} e^{-i \beta \hat{J}_{y} / \hbar} e^{-i \gamma \hat{J}_{z} / \hbar}$ [35]. $\hat{\mathbf{J}}^{2}$ remains unchanged, and the common eigenstates of $\hat{\mathbf{J}}^{2}$ and $\hat{L}_{z}$ read $\left|J_{k}, m_{k}\right\rangle=\hat{R}(\alpha, \beta, \gamma)\left|J_{k}, m_{k}\right\rangle$ $(k=e, g)$. The elements of the basis transformation matrix $\left\langle J_{k}, m_{k} \mid J_{k}, m_{k}^{\prime}\right\rangle$ are given by the so-called Wigner functions $\overline{\mathcal{D}_{m_{k}, m_{k}^{\prime}}^{\left(J_{k}\right)}}(\alpha, \beta, \gamma)=e^{-i\left(m_{k} \alpha+m_{k}^{\prime} \gamma\right)} d_{m_{k}, m_{k}^{\prime}}^{\left(J_{k}\right)}(\beta)$, with $d_{m, m^{\prime}}^{(J)}(\beta)=A_{m, m^{\prime}}(J) B_{m, m^{\prime}}(\beta) P_{J-m^{\prime}}^{\left(m^{\prime}-m, m^{\prime}+m\right)}(\cos \beta), \quad$ where $A_{m, m^{\prime}}(J)=\sqrt{\left[\left(J+m^{\prime}\right)!\left(J-m^{\prime}\right)!\right] /[(J+m)!(J-m)!}$, $B_{m, m^{\prime}}(\beta)=[\sin (\beta / 2)]^{m^{\prime}-m}[\cos (\beta / 2)]^{m^{\prime}+m}$, and where the $P_{n}^{(a, b)}(z)$ are the Jacobi polynomials [35]. If $\rho(t)$ and $\rho(t)$ denote the density matrices of the atomic state $\hat{\rho}(t)$ in the $\left\{\left|J_{k}, m_{k}\right\rangle\right\}$ and $\left\{\left|\underline{J_{k}, m_{k}}\right\rangle\right\}$ bases, respectively, we get

$$
\begin{equation*}
\underline{\rho}(t)=\mathcal{D}(\alpha, \beta, \gamma)^{\dagger} \rho(t) \mathcal{D}(\alpha, \beta, \gamma) \tag{A1}
\end{equation*}
$$

with $\quad \mathcal{D}(\alpha, \beta, \gamma)=\oplus_{k=e, g} \mathcal{D}^{\left(J_{k}\right)}(\alpha, \beta, \gamma), \quad$ where $\mathcal{D}^{\left(J_{k}\right)}(\alpha, \beta, \gamma)$ is the unitary matrix of elements $\mathcal{D}_{m_{k}, m_{k}^{\prime}}^{\left(J_{k}\right)}(\alpha, \beta, \gamma)$. It follows that the associated OBE column vector $\mathbf{x}(t)$ transforms according to

$$
\begin{equation*}
\underline{\mathbf{x}}(t)=T(\alpha, \beta, \gamma) \mathbf{x}(t) \tag{A2}
\end{equation*}
$$

with the transformation matrix

$$
T(\alpha, \beta, \gamma)=\left(\begin{array}{cc}
T_{o o}(\alpha, \beta, \gamma) & 0  \tag{A3}\\
0 & T_{\xi \xi}(\alpha, \beta, \gamma)
\end{array}\right)
$$

where

$$
T_{\xi \xi}(\alpha, \beta, \gamma)=\left(\begin{array}{cc}
T_{p p}(\beta) & T_{p Z}(\alpha, \beta)  \tag{A4}\\
T_{Z p}(\beta, \gamma) & T_{Z Z}(\alpha, \beta, \gamma)
\end{array}\right)
$$

with blocks $T_{o o}(\alpha, \beta, \gamma), T_{p p}(\beta), T_{p Z}(\alpha, \beta), T_{Z p}(\beta, \gamma)$, and $T_{Z Z}(\alpha, \beta, \gamma)$ as explicitly detailed below. The OBEs from Eq. (11) in the $\underline{S}$ reference frame then read

$$
\begin{equation*}
\frac{d}{d t} \underline{\mathbf{x}}(t)=\underline{A}(t) \underline{\mathbf{x}}(t)+\underline{\mathbf{b}} \tag{A5}
\end{equation*}
$$

with

$$
\begin{equation*}
\underline{A}(t)=T(\alpha, \beta, \gamma) A(t) T(\alpha, \beta, \gamma)^{-1} \tag{A6}
\end{equation*}
$$

and

$$
\begin{equation*}
\underline{\mathbf{b}}=T(\alpha, \beta, \gamma) \mathbf{b} \tag{A7}
\end{equation*}
$$

Thanks to the orthogonality relations of the ClebschGordan coefficients, to the orthogonality of the $d^{(1)}(\beta)$ matrices of elements $d_{m, m^{\prime}}^{(1)}(\beta)$, to the transformation law of the spherical components of any three-dimensional space vector $\boldsymbol{v}, \quad\left(\underline{v}_{1}, \underline{v}_{0}, \underline{v}_{-1}\right)^{T}=$ $\mathcal{D}^{(1)}(\alpha, \beta, \gamma)^{T}\left(v_{1}, v_{0}, v_{-1}\right)^{T}$, and to the identities $\mathcal{C}_{m_{g}}^{(q)} d_{m_{e}, m_{g}+q}^{\left(J_{e}\right)}(\beta)=\sum_{q^{\prime}} \mathcal{C}_{m_{e}-q^{\prime}}^{\left(q^{\prime}\right)} d_{m_{e}-q^{\prime}, m_{g}}^{\left(J_{g}\right)}(\beta) d_{q^{\prime}, q}^{(1)}(\beta) \quad$ and $\mathcal{C}_{m_{e}-q}^{(q)} d_{m_{e}-q, m_{g}}^{\left(J_{g}\right)}(\beta)=\sum_{q^{\prime}} \mathcal{C}_{m_{g}}^{\left(q^{\prime}\right)} d_{m_{e}, m_{g}+q^{\prime}}^{\left(J_{e}\right)}(\beta) d_{q, q^{\prime}}^{(1)}(\beta) \quad$ (see, e.g., Ref. [36]), which imply, $\forall m_{k_{1}}, m_{k_{2}}=-J_{k}, \ldots, J_{k}$ $(k=e, g), \quad \sum_{q} \mathcal{C}_{m_{g_{1}}}^{(q)} d_{m_{e_{1}}, m_{g_{1}}+q}^{\left(J_{e}\right)}(\beta) \mathcal{C}_{m_{g_{2}}}^{(q)} d_{m_{e_{2}}, m_{g_{2}+q}}^{\left(U_{e}\right)}(\beta)=$ $\sum_{q} \mathcal{C}_{m_{e_{1}-q}}^{(q)} d_{m_{e_{1}-q, m_{g_{1}}}^{(J g)}}^{\left(J_{1}\right)} \mathcal{C}_{m_{e_{2}}-q}^{(q)} d_{m_{e_{2}-q, m_{g_{2}}}^{\left(J_{g}\right)}}^{(\beta) \text {, the explicit }}$ calculation of Eqs. (A6) and (A7) yields, as expected,

$$
\begin{equation*}
\underline{A}(t)=-\Gamma A_{0}+\operatorname{Im}\left(\boldsymbol{\Omega}(t) \cdot \underline{\mathbf{e}}_{C}\right) \tag{A8}
\end{equation*}
$$

and $\underline{\mathbf{b}}=\mathbf{b}$, where $\underline{\mathbf{e}}_{C}=\sum_{q} C^{(q)} \underline{\mathbf{e}}_{q}$, with $\underline{\mathbf{e}}_{q}$ the $\underline{S}$ lower-index spherical basis, such that $\boldsymbol{\Omega}(t) \cdot \underline{\mathbf{e}}_{C}=\sum_{q} \underline{\Omega}_{q}(t) C^{(q)}$.

Similarly, the transformation law $\underline{\mathbf{x}}_{o}(t)=T_{o o}(\alpha, \beta, \gamma) \mathbf{x}_{o}(t)$ [see Eq. (A2)] directly yields the standard contravariant transformation law $\left.\quad \underline{\chi}_{o}^{(1)}, \underline{\chi}_{o}^{(0)}, \underline{\chi}_{o}^{(-1)}\right)^{T}=$ $\mathcal{D}^{(1)}(\alpha, \beta, \gamma)^{\dagger}\left(\chi_{o}^{(1)}, \chi_{o}^{(0)}, \chi_{o}^{(-1)}\right)^{T}$ that proves the vectorial character of $\chi_{o}(t)$ [see Eq. (25)].

## 1. $T_{o o}(\alpha, \beta, \gamma)$ BLOCK

In accordance with Eq. (8), the $T_{o o}(\alpha, \beta, \gamma)$ block is structured into vertically and horizontally ordered subblocks $T_{o o}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \beta, \gamma)$, with respective indices $\Delta m$ and $\Delta m^{\prime}$ both ranging from $-\left(J_{e}+J_{g}\right)$ to $J_{e}+J_{g}$. The subblocks $\quad T_{o o}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \beta, \gamma) \quad \operatorname{read} \quad \tilde{T}_{o o}^{\left(\Delta m, \Delta m^{\prime}\right)}(\beta) \otimes$ $U_{+}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma)$, with matrix elements $\left(\tilde{T}_{o o}^{\left(\Delta m, \Delta m^{\prime}\right)}(\beta)\right)_{m, m^{\prime}}=$ $d_{m^{\prime}, m}^{\left(J_{g}\right)}(\beta) d_{m^{\prime}+\Delta m^{\prime}, m+\Delta m}^{\left(J_{e}\right)}(\beta) \quad\left(m=m_{-}^{(\Delta m)}, \ldots, m_{+}^{(\Delta m)} \quad\right.$ and $\left.m^{\prime}=m_{-}^{\left(\Delta m^{\prime}\right)}, \ldots, m_{+}^{\left(\Delta m^{\prime}\right)}\right)$ and where
$U_{ \pm}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma)=\left(\begin{array}{cc}c_{ \pm}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma) & s_{ \pm}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma) \\ \mp s_{ \pm}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma) & \pm c_{ \pm}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma)\end{array}\right)$,
with $\quad c_{ \pm}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma)=\cos \left(\Delta m^{\prime} \alpha \pm \Delta m \gamma\right) \quad$ and $s_{ \pm}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma)=\sin \left(\Delta m^{\prime} \alpha \pm \Delta m \gamma\right)$.

## 2. $\boldsymbol{T}_{p p}(\beta)$ BLOCK

The $T_{p p}(\beta)$ block is structured into four subblocks (one is zero) as

$$
T_{p p}(\beta)=\left(\begin{array}{cc}
T_{p_{e} p_{e}}(\beta) & 0 \\
T_{p_{g} p_{e}}(\beta) & T_{p_{g} p_{g}}(\beta)
\end{array}\right)
$$

(A10)
with subblock elements $\left(T_{p_{e} p_{e}}(\beta)\right)_{m_{e}, m_{e}^{\prime}}=\left(d_{m_{e}^{\prime}, m_{e}}^{\left(J_{e}\right)}(\beta)\right)^{2}$, $\left(T_{p_{g} p_{e}}(\beta)\right)_{m_{g}, m_{e}^{\prime}}=-\left(d_{-J_{g}, m_{g}}^{\left(J_{g}\right)}(\beta)\right)^{2}$, and $\left(T_{p_{g} p_{g}}(\beta)\right)_{m_{g}, m_{g}^{\prime}}=$ $\left(d_{m_{g}^{\prime}, m_{g}}^{\left(J_{g}\right)}(\beta)\right)^{2}-\left(d_{-J_{g}, m_{g}}^{\left(J_{g}\right)}(\beta)\right)^{2}, \quad$ where $\quad m_{k}, m_{k}^{\prime}=-J_{k}+$ $\delta_{k, g}, \ldots, J_{k}(k=e, g)$.

## 3. $\boldsymbol{T}_{\boldsymbol{Z p}}(\beta, \gamma)$ BLOCK

The $T_{Z p}(\beta, \gamma)$ block is similarly structured into four subblocks (among which one is zero) as

$$
T_{Z p}(\beta, \gamma)=\left(\begin{array}{cc}
T_{Z_{e} p_{e}}(\beta, \gamma) & 0  \tag{A11}\\
T_{Z_{g} p_{e}}(\beta, \gamma) & T_{Z_{g} p_{g}}(\beta, \gamma)
\end{array}\right)
$$

where the subblocks $T_{Z_{k} p l}(\beta, \gamma)(k, l=e, g)$ are themselves further divided [in accordance with Eq. (10)] into vertically ordered subsubblocks $T_{Z_{k} p l}^{(\Delta m)}(\beta, \gamma)$ indexed with $\Delta m=1, \ldots, 2 J_{k}$. The subsubblocks $T_{Z_{k} p l}^{(\Delta m)}(\beta, \gamma)$ read $\tilde{T}_{Z_{k} p l}^{(\Delta m)}(\beta) \otimes(\cos (\Delta m \gamma),-\sin (\Delta m \gamma))^{T}$, with matrix elements $\quad\left(\tilde{T}_{Z_{e} p_{e}}^{(\Delta m)}(\beta)\right)_{m_{e}, m_{e}^{\prime}}=d_{m_{e}^{\prime}, m_{e}}^{\left(J_{e}\right)}(\beta) d_{m_{e}^{\prime}, m_{e}+\Delta m}^{\left(J_{e}\right)}(\beta)$, $\left(\tilde{T}_{Z_{g} p_{e}}^{(\Delta m)}(\beta)\right)_{m_{g}, m_{e}^{\prime}}=-d_{-J_{g}, m_{g}}^{\left(J_{g}\right)}(\beta) d_{-J_{g}, m_{g}+\Delta m}^{\left(J_{g}\right)}(\beta)$,
and $\quad\left(\tilde{T}_{Z_{g} p_{g}}^{(\Delta m)}(\beta)\right)_{m_{g}, m_{g}^{\prime}}=d_{m_{g}^{\prime}, m_{g}}^{\left(J_{g}\right)}(\beta) d_{m_{g}^{\prime}, m_{g}+\Delta m}^{\left(J_{g}\right)}(\beta)-$ $d_{-J_{g}, m_{g}}^{\left(J_{g}\right)}(\beta) d_{-J_{g}, m_{g}+\Delta m}^{\left(J_{g}\right)}(\beta)$, where $m_{k}=-J_{k}, \ldots, J_{k}-\Delta m$ and $m_{k}^{\prime}=-J_{k}+\delta_{k, g}, \ldots, J_{k}(k=e, g)$.

## 4. $\boldsymbol{T}_{p z}(\alpha, \beta)$ BLOCK

The $T_{p Z}(\alpha, \beta)$ block is structured into two diagonal subblocks as

$$
T_{p} Z(\alpha, \beta)=\left(\begin{array}{cc}
T_{p_{c}} z_{e}(\alpha, \beta) & 0  \tag{A12}\\
0 & T_{p_{g} z_{g}}(\alpha, \beta)
\end{array}\right)
$$

where the subblocks $T_{p k} Z_{k}(\alpha, \beta)(k=e, g)$ are themselves further divided [in accordance with Eq. (10)] into horizontally ordered subsubblocks $T_{p_{k} Z_{k}}^{(\Delta m)}(\alpha, \beta)$ indexed with $\Delta m=1, \ldots, 2 J_{k}$. The subsubblocks $\quad T_{p_{k} Z_{k}}^{(\Delta m)}(\alpha, \beta)$ read $\tilde{T}_{p_{k} Z_{k}}^{(\Delta m)}(\beta) \otimes(\cos (\Delta m \alpha), \sin (\Delta m \alpha))$, with matrix elements $\left(\tilde{T}_{p_{k} Z_{k}}^{(\Delta m)}(\beta)\right)_{m_{k}, m_{k}^{\prime}}=2 d_{m_{k}^{\prime}, m_{k}}^{\left(J_{k}\right)}(\beta) d_{m_{k}^{\prime}+\Delta m^{\prime}, m_{k}}^{\left.(J)_{k}\right)}(\beta)$, where $m_{k}=-J_{k}+\delta_{k, g}, \ldots, J_{k}$ and $m_{k}^{\prime}=-J_{k}, \ldots, J_{k}-\Delta m$.

## 5. $T_{z z}(\alpha, \beta, \gamma)$ BLOCK

The $T_{Z Z}(\alpha, \beta, \gamma)$ block is similarly structured into two diagonal subblocks as

$$
T_{Z Z}(\alpha, \beta, \gamma)=\left(\begin{array}{cc}
T_{Z_{e} Z_{e}}(\alpha, \beta, \gamma) & 0  \tag{A13}\\
0 & T_{Z_{g} Z_{g}}(\alpha, \beta, \gamma)
\end{array}\right),
$$

where the subblocks $T_{Z_{k} Z_{k}}(\alpha, \beta, \gamma) \quad(k=e, g) \quad$ are themselves divided [in accordance with Eq. (10)] into vertical and horizontal subsubblocks $T_{Z_{k} Z_{k}}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \beta, \gamma)$, with respective indices $\Delta m=1, \ldots, 2 J_{k}$ and $\Delta m^{\prime}=$ $1, \ldots, 2 J_{k}^{\prime}$. The subsubblocks $T_{Z_{k} Z_{k}}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \beta, \gamma) \mathrm{read}$ $\sum_{\varepsilon= \pm} \tilde{T}_{Z_{k} Z_{k}, \varepsilon}^{\left(\Delta m, \Delta m^{\prime}\right)}(\beta) \otimes U_{\varepsilon}^{\left(\Delta m, \Delta m^{\prime}\right)}(\alpha, \gamma)$, with matrix elements $\left(\tilde{T}_{Z_{k} Z_{k},+}^{\left(\Delta m, \Delta m^{\prime}\right)}(\beta)\right)_{m_{k}, m_{k}^{\prime}}=d_{m_{k}^{\prime}, m_{k}}^{\left(J_{k}\right)}(\beta) d_{m_{k}^{\prime}+\Delta m^{\prime}, m_{k}+\Delta m}^{\left(J_{k}\right)}(\beta)$ and $\quad\left(\tilde{T}_{Z_{k} Z_{k},-}^{\left(\Delta m, \Delta m^{\prime}\right)}(\beta)\right)_{m_{k}, m_{k}^{\prime}}=d_{m_{k}^{\prime}+\Delta m^{\prime}, m_{k}}^{\left.(J)_{k}\right)}(\beta) d_{m_{k}^{\prime}, m_{k}+\Delta m}^{\left(J_{k}\right)}(\beta)$, where $m_{k}=-J_{k}, \ldots, J_{k}-\Delta m$ and $m_{k}^{\prime}=-J_{k}, \ldots, J_{k}-$ $\Delta m^{\prime}(k=e, g)$.

## APPENDIX B: EXPLICIT VALUE OF THE $\left(\boldsymbol{C}_{\xi \xi}\right)_{\boldsymbol{q}^{\prime}}^{\boldsymbol{q}}$ MATRICES

The matrices $\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}=-C_{\xi o}^{(q)} C_{o \xi}^{\left(q^{\prime}\right) *}$ are structured into four blocks as

$$
\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}=\left(\begin{array}{ll}
\left(C_{p p}\right)_{q^{\prime}}^{q} & \left(C_{p Z}\right)_{q^{\prime}}^{q}  \tag{B1}\\
\left(C_{Z p}\right)_{q^{\prime}}^{q} & \left(C_{Z Z}\right)_{q^{\prime}}^{q}
\end{array}\right)
$$

with $\left(C_{r s}\right)_{q^{\prime}}^{q}=-C_{r o}^{(q)} C_{o s}^{\left(q^{\prime}\right)^{*}}(r, s=p, Z)$. These blocks are themselves further divided into four subblocks as

$$
\left(C_{r s}\right)_{q^{\prime}}^{q}=\left(\begin{array}{ll}
\left(C_{r_{e} s_{e}}\right)_{q^{\prime}}^{q} & \left(C_{r_{e} s_{g}}\right)_{q^{\prime}}^{q}  \tag{B2}\\
\left(C_{r_{g} s_{e}}\right)_{q^{\prime}}^{q} & \left(C_{r_{g} s_{g}}\right)_{q^{\prime}}^{q}
\end{array}\right)
$$

where again $\left(C_{r_{k} l}\right)_{q^{\prime}}^{q}=-C_{r_{k} o}^{(q)} C_{o s_{l}}^{\left(q^{\prime}\right)^{*}} \quad(k, l=e, g)$. These subblocks are detailed below.

## 1. $\left(\boldsymbol{C}_{\boldsymbol{p}_{k} \boldsymbol{p}_{l}}\right)_{\boldsymbol{q}^{\prime}}^{\boldsymbol{q}}$ SUBBLOCKS

For $k, l=e, g$, we have $\left(C_{p_{k} p_{l}}\right)_{q^{\prime}}^{q}=\left(\tilde{C}_{p_{k} p_{l}}\right)_{q}^{q} \delta_{q, q^{\prime}}$, with $\left(\tilde{C}_{p k p l}\right)_{q}^{q}=-\tilde{C}_{p k o}^{(q)} \tilde{C}_{o p l}^{(q)}$. The $\left(\tilde{C}_{p k p l}\right)_{q}^{q}$ matrix elements are indexed with the two numbers $m=-J_{k}+\delta_{k, g}, \ldots, J_{k}$ and $m^{\prime}=-J_{l}+\delta_{l, g}, \ldots, J_{l}$. They are a priori only nonzero if $m-n_{k} q \in\left\{m_{-}^{(q)}, \ldots, m_{+}^{(q)}\right\}$, in which case they read explicitly $\quad\left[\left(\tilde{C}_{p_{k} p_{l}}\right)_{q}^{q}\right]_{m, m^{\prime}}=\tilde{n}_{k}\left(\mathcal{C}_{m-n_{k} q}^{(q)}\right)^{2}\left(\delta_{m,-J_{g}+n_{k} q}+\right.$ $\left.\tilde{n}_{l} \delta_{m^{\prime}, m+\left(n_{l}-n_{k}\right) q}\right) / 2$. All $\left(C_{p p}\right)_{q^{\prime}}^{q}$ matrix elements are real numbers.

## 2. $\left(\boldsymbol{C}_{\boldsymbol{p}_{k} \boldsymbol{z}_{l}}\right)_{\boldsymbol{q}^{\prime}}^{\boldsymbol{q}}$ SUBBLOCKS

For $k, l=e, g$, we have

$$
\begin{equation*}
\left(C_{p_{k} Z_{l}}\right)_{q^{\prime}}^{q}=\left(\left(\tilde{C}_{p_{k} Z_{l}}^{(1)}\right)_{q^{\prime}}^{q}\left(\tilde{C}_{p_{k} Z_{l}}^{(2)}\right)_{q^{\prime}}^{q} 0\right) \tag{B3}
\end{equation*}
$$

The 0 block is of dimension $\operatorname{dim} \mathbf{x}_{p_{k}} \times \sum_{i=3}^{2 J} \operatorname{dim} \mathbf{x}_{Z_{l}}^{(i)}$ and, for $j=1,2$,

$$
\left.\left(\tilde{C}_{p k}^{(j)}\right)_{l}\right)_{q^{\prime}}^{q}= \begin{cases}0_{\operatorname{dim} \mathbf{x}_{p_{k}} \times \operatorname{dim} \mathbf{x}_{Z_{l}}^{(j)}} & \text { if }|\Delta q| \neq j  \tag{B4}\\ \left(\check{C}_{p k}^{(j)} Z_{l}\right)_{q^{\prime}}^{q} \otimes(1, \operatorname{sgn}(\Delta q) i) & \text { otherwise }\end{cases}
$$

with $\quad \Delta q \equiv q^{\prime}-q \quad$ and $\quad\left(\check{C}_{p k}^{(j)} Z_{l}\right)_{q^{\prime}}^{q}=-\tilde{C}_{p k o}^{(q)} \tilde{C}_{o Z_{l},-\operatorname{sgn}(\Delta q)}^{(q,|\Delta q|)}$ for $\Delta q \neq 0$ (see Section 2). Hence, $\left(C_{p k} z_{l}\right)_{q}^{q}=0, \forall q$.

The $\left(\check{C}_{p k}^{(j)} Z_{l}\right)_{q^{\prime}}^{q}$ matrix elements are indexed with the two numbers $m=-J_{k}+\delta_{k, g}, \ldots, J_{k}$ and $m^{\prime}=-J_{l}, \ldots, J_{l}-|\Delta q|$. They are a priori only nonzero if $m-n_{k} q \in\left\{m_{-}^{(q)}, \ldots, m_{+}^{(q)}\right\}$, in which case they read explicitly $\left[\left(\check{C}_{p k}^{(j)} Z_{l}\right)_{q^{\prime}}^{q}\right]_{m, m^{\prime}}=$ $\left(\tilde{n}_{k} \tilde{n}_{l} \mathcal{C}_{m-n_{k} q}^{(q)} \mathcal{C}_{m-n_{k} q+\left(n_{l}-1\right) \Delta q}^{\left(q^{\prime}\right)} \delta_{m^{\prime}, m+\left(\tilde{n}_{l} q^{\prime}-\tilde{n}_{k} q-j\right) / 2}\right) / 2$.

## 3. $\left(\boldsymbol{C}_{\boldsymbol{z}_{\boldsymbol{k}} \boldsymbol{p}_{\boldsymbol{I}}}\right)_{\boldsymbol{q}^{\boldsymbol{q}}}$ SUBBLOCKS

For $k, l=e, g$, we have

$$
\left(C_{Z_{k} p l}\right)_{q^{\prime}}^{q}=\left(\begin{array}{c}
\left(\tilde{C}_{Z_{k p l}}^{(1)}\right)_{q^{\prime}}^{q}  \tag{B5}\\
\left(\tilde{C}_{Z_{k p l}}^{(2)}\right)_{q^{\prime}}^{q} \\
0
\end{array}\right)
$$

The 0 block is of dimension $\sum_{i=3}^{2 J_{k}} \operatorname{dim} \mathbf{x}_{Z_{k}}^{(i)} \times \operatorname{dim} \mathbf{x}_{p_{l}}$ and, for $j=1,2$,

$$
\left(\tilde{C}_{Z_{k} p_{l}}^{(j)}\right)_{q^{\prime}}^{q}= \begin{cases}0_{\operatorname{dim}} \mathbf{x}_{Z_{k}}^{(j)} \times \operatorname{dim} \mathbf{x}_{p_{l}} & \text { if }|\Delta q| \neq j  \tag{B6}\\ \left(\check{C}_{Z_{k} p_{l}}^{(j)}\right)_{q^{\prime}}^{q} \otimes(1, \operatorname{sgn}(\Delta q) i)^{T} & \text { otherwise }\end{cases}
$$

with $\left(\check{C}_{Z_{k p l}}^{(j)}\right)_{q^{\prime}}^{q}=-\tilde{C}_{Z_{k} o, \operatorname{sgn}(\Delta q)}^{\left(|\Delta q|, q^{\prime}\right)} \tilde{C}_{o p l}^{\left(q^{\prime}\right)}$ for $\Delta q \neq 0$, where $\tilde{C}_{Z_{k} o, \varepsilon}^{\left(|\Delta q|, q^{\prime}\right)}=-\tilde{C}_{o Z_{k}, \varepsilon}^{\left(q^{\prime},|\Delta q|\right)^{T}}$ for $\epsilon= \pm 1$ (see Section 2). Hence, $\left(C_{Z_{k p l}}\right)_{q}^{q}=0, \forall q$. The $\left(\check{C}_{Z_{k} p_{l}}^{(j)}\right)_{q^{\prime}}^{q}$ matrix elements are indexed with the two numbers $m=-J_{k}, \ldots, J_{k}-|\Delta q|$ and $m^{\prime}=-J_{l}+\delta_{l, g}, \ldots, J_{l}$. They are a priori only nonzero if $\quad m-n_{k} q-[1-\operatorname{sgn}(\Delta q)] \Delta q / 2 \in\left\{m_{-}^{\left(q^{\prime}\right)}, \ldots, m_{+}^{\left(q^{\prime}\right)}\right\}$, in which case they read explicitly $\left[\left(\check{C}_{Z_{k} p_{l}}^{(j)}\right)_{q^{\prime}}^{q}\right]_{m, m^{\prime}}=$ $\left(\tilde{n}_{k} \mathcal{C}_{-J_{g}}^{\left(q^{\prime}\right)} \mathcal{C}_{-J_{g}-\left(n_{k}-1\right) \Delta q}^{(q)} \delta_{m,-J_{g}+\left(q^{\prime}+\tilde{n}_{k} q-j\right) / 2}+\right.$ $\left.\tilde{n}_{k} \tilde{n}_{l} \mathcal{C}_{\left.m^{\prime}-n_{l} q^{( } \mathcal{C}^{\prime}\right)} \mathcal{C}_{m^{\prime}-n_{l} q^{\prime}-\left(n_{k}-1\right) \Delta q}^{(q)} \delta_{m^{\prime}, m+\left(\tilde{n}_{l} q^{\prime}-\tilde{n}_{k} q+j\right) / 2}\right) / 4$.
We note that $\left(C_{p_{k} Z_{l}}\right)_{q^{\prime}}^{q} \neq-\left[\left(C_{Z_{l} p_{k}}\right)_{q^{\prime}}^{q}\right]^{T}$.

## 4. $\left(\boldsymbol{C}_{z_{k} z_{l}}\right)_{\boldsymbol{q}^{\prime}}^{\boldsymbol{q}}$ SUBBLOCKS

For $k, l=e, g$, we have

$$
\begin{align*}
\left(C_{Z_{k} Z_{l}}\right)_{q^{\prime}}^{q}= & \sum_{\epsilon= \pm 1}\left(\tilde{C}_{Z_{k} Z_{l}, \epsilon}\right)_{q^{\prime}}^{q} \otimes\left(\begin{array}{cc}
1 & -\epsilon i \\
\epsilon i & 1
\end{array}\right) \\
& +\left(\tilde{C}_{Z_{k} Z_{l}}\right)_{q}^{q} \otimes\left(\begin{array}{cc}
1 & -q i \\
-q i & -1
\end{array}\right) \delta_{q^{\prime},-q} \tag{B7}
\end{align*}
$$

with $\left(\tilde{C}_{Z_{k} Z_{l}, \varepsilon}\right)_{q^{\prime}}^{q}$ and $\left(\tilde{C}_{Z_{k} Z_{l}}\right)_{q}^{q}$ as described below.
If $\operatorname{diag}_{p}\left(X_{1}, \ldots, X_{n}\right)$ denotes the rectangular matrix whose elements are matrix blocks, with $X_{1}, \ldots, X_{n}$ the only nonzero such elements exactly located on the $p$ th superdiagonal (or subdiagonal if $p<0$ ) of the rectangular matrix, then we have

$$
\begin{equation*}
\left(\tilde{C}_{Z_{k} Z_{l}, \epsilon}\right)_{q^{\prime}}^{q}=\operatorname{diag}_{-\epsilon \Delta q}\left(\left(\tilde{C}_{Z_{k} Z_{l, \epsilon}}^{\left(\Delta m_{-}\right)}\right)_{q^{\prime}}^{q}, \ldots,\left(\tilde{C}_{Z_{k} Z_{l, \epsilon}}^{\left(\Delta m_{+}\right)}\right)_{q^{\prime}}^{q}\right) \tag{B8}
\end{equation*}
$$

where $\quad \Delta m_{-}=\max [1,1+\epsilon \Delta q], \quad \Delta m_{+}=\Delta m_{-}+$ $2 \min \left(J_{e}, J_{g}\right)-1, \quad$ and, for $\quad \Delta m=\Delta m_{-}, \ldots, \Delta m_{+}$, $\left(\tilde{C}_{Z_{k} Z_{l, \epsilon}}^{(\Delta m)}\right)_{q^{\prime}}^{q}$ is a matrix block of dimension $\left(\operatorname{dim} \mathbf{x}_{Z_{k}}^{(\Delta m)} / 2\right) \times$ $\left(\operatorname{dim} \mathbf{x}_{Z_{l}}^{(\Delta m-\epsilon \Delta q)} / 2\right)$. These blocks are a priori only nonzero for $\Delta m+\epsilon q \leq J_{e}+J_{g}$, in which case they identify
to $-\tilde{C}_{Z_{k} 0, \epsilon}^{(\Delta m, q+\epsilon \Delta m)} \tilde{C}_{o Z_{l, \epsilon}}^{(q+\epsilon \Delta m, \Delta m-\epsilon \Delta q)}$, with matrix elements $\left[\left(\tilde{C}_{Z_{k} Z_{l}, \epsilon}^{(\Delta m)}\right)_{q^{\prime}}^{q}\right]_{m, m^{\prime}}=\left(\tilde{n}_{k} \tilde{n}_{l} / 4\right) \mathcal{C}_{m-\left(1+\tilde{n}_{k}\right) q / 2+\left(1-\epsilon \tilde{n}_{k}\right) \Delta m / 2}^{(q)}$ $\mathcal{C}_{m+\left(1-\epsilon \tilde{n}_{l}\right) \Delta m / 2-\left(\tilde{n}_{k} q-\tilde{n}_{l} \Delta q+q^{\prime}\right) / 2} \delta_{m^{\prime}, \mu}$, where $\quad \mu=m+\left(\tilde{n}_{l} q^{\prime}\right.$ $\left.-\tilde{n}_{k} q+\epsilon \Delta q\right) / 2, \quad m=-J_{k}, \ldots, J_{k}-\Delta m, \quad$ and $\quad m^{\prime}=$ $-J_{l}, \ldots, J_{l}-\Delta m+\epsilon \Delta q$.

We also have

$$
\left(\tilde{C}_{Z_{k} Z_{l}}\right)_{q}^{q}=\left\{\begin{array}{cl}
0_{\left(\operatorname{dim} \mathbf{x}_{Z_{k}} / 2\right) \times\left(\operatorname{dim} \mathbf{x}_{Z_{l}} / 2\right)} & \text { if } q=0  \tag{B9}\\
\left(\begin{array}{cc}
\left(\check{C}_{Z_{k} Z_{l}}\right)_{q}^{q} & 0 \\
0 & 0_{d_{k} \times d_{l}}
\end{array}\right) & \text { otherwise }
\end{array}\right.
$$

with, for $k=e, g, d_{k} \equiv \sum_{i=2}^{2 J_{k}} \operatorname{dim} \mathbf{x}_{Z_{k}}^{(i)} / 2=J_{k}\left(2 J_{k}-1\right)$, and $\left(\check{C}_{Z_{k} Z_{l}}\right)_{q}^{q}=-\tilde{C}_{Z_{k} 0,-q}^{(1,0)} \tilde{C}_{o Z_{l, q}}^{(0,1)}$. The $\left(\check{C}_{Z_{k} Z_{l}}\right)_{q}^{q}$ matrix elements are indexed with the two numbers $m=-J_{k}, \ldots, J_{k}-1$ and $m^{\prime}=-J_{l}, \ldots, J_{l}-1$. They read explicitly $\left[\left(\check{C}_{Z_{k} Z_{l}}\right)_{q}^{q}\right]_{m, m^{\prime}}=$ $\left(\tilde{n}_{k} \tilde{n}_{l} / 4\right) \mathcal{C}_{m+(1-q) / 2}^{(q)} \mathcal{C}_{m^{\prime}+(1+q) / 2}^{(-q)} \delta_{m^{\prime}, m-\left(\tilde{n}_{k}+\tilde{n}_{l}\right) q / 2}$.

The $\left(C_{Z_{k} Z_{l}}\right)_{q^{\prime}}^{q}$ subblocks are such that $\left(C_{Z Z}\right)_{q^{\prime}}^{q}=\left[\left(C_{Z Z}\right)_{q}^{q^{\prime}}\right]^{\dagger}$ and $\left(C_{Z_{g} Z_{e}}\right)_{q^{\prime}}^{q}=\left[\left(C_{Z_{e} Z_{g}}\right)_{q^{\prime}}^{q}\right]^{T}, \forall q, q^{\prime}$. In addition, $\sum_{q}\left(C_{Z Z}\right)_{q}^{q}$ is a real matrix.

Funding. Fonds de la Recherche Scientifique - FNRS (2.5020.11, 4.4512.08).

Acknowledgment. T. Bastin acknowledges financial support of the Belgian F.R.S.-FNRS through IISN. The authors thank the Consortium des Équipements de Calcul Intensif (CÉCI), funded by the Fonds de la Recherche Scientifique de Belgique (F.R.S.-FNRS) and by the Walloon Region, for providing the computational resources.
Disclosures. The authors declare no conflicts of interest.
Data Availability. Data underlying the results presented in this paper are not publicly available at this time but may be obtained from the authors upon reasonable request.

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24. In a Cartesian reference frame $\left\{\mathbf{e}_{x}, \mathbf{e}_{y}, \mathbf{e}_{z}\right\}$, the upper-index spherical basis vectors explicitly read $\mathbf{e}^{ \pm 1}=\mp\left(\mathbf{e}_{x} \mp i \mathbf{e}_{y}\right) / \sqrt{2}$ and $\mathbf{e}^{0}=\mathbf{e}_{z}$ [see, e.g., M. Auzinsh, D. Budker, and S. M. Rochester, Optically Polarized Atoms (Oxford University Press, 2009)].
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27. The column vector $\mathbf{x}(t)$ is bounded since it is composed (up to additive constants and multiplicative complex exponentials) of density matrix populations and coherences. The populations are at all times comprised between 0 and 1 , and the coherences are upper bounded by the maximal population value since the density matrix is hermitian positive semi-definite [37].
28. The system in Eq. (19) is only defined if all $A_{\xi \xi}^{(n)}+B_{\xi \xi}^{(n, 0)}$ matrices are invertible, which is ensured if the periodic regime is unique. Otherwise, the following formalism does not apply. This is, for instance, the case for $\Delta J=-1$ and all waves with the same polarization $\boldsymbol{\epsilon}_{j}\left(\lambda_{m}=0\right.$ and det $\left.\left(A_{\xi \xi}^{(0)}+B_{\xi \xi}^{(0,0)}\right)=0\right)$.
29. Such suitable matrices can be given by (see, e.g., Ref. [37]): $Q_{\xi \xi}^{(n)}=0$ if $\quad \mathbf{x}_{\xi}^{(n)}=0$; otherwise, $\quad Q_{\xi \xi}^{(n)}=\left(e^{i \theta}\left\|\mathbf{x}_{\xi}^{(n)}\right\| /\left\|\mathbf{x}_{\xi}^{(0)}\right\|\right) \mathbb{1}_{\xi} \quad$ if $\quad \mathbf{x}_{\xi}^{(n)} /\left\|\mathbf{x}_{\xi}^{(n)}\right\|=$ $e^{i \theta}\left(\mathbf{x}_{\xi}^{(0)} /\left\|\mathbf{x}_{\xi}^{(0)}\right\|\right) \quad\left(\theta \in\left[0,2 \pi[) ; \quad\right.\right.$ otherwise, $\quad Q_{\xi \xi}^{(n)}=\left(\left\|\mathbf{x}_{\xi}^{(n)}\right\| /\left\|\mathbf{x}_{\xi}^{(0)}\right\|\right) U_{\xi \xi}^{(n)}$. In the latter, $\cup_{\xi \xi}^{(n)}$ is the unitary matrix $e^{i \phi^{(n)}} V_{\xi \xi}^{(n)}$, where $\phi^{(n)}$ is the phase of the complex number $\mathbf{x}_{\xi}^{(0) *} \cdot \mathbf{x}_{\xi}^{(n)}$, conventionally set to 0 if the complex number is zero, and where $V_{\xi \xi}^{(n)}$ is the Householder matrix $V_{\xi \xi}^{(n)}=$ $\mathbb{1}_{\xi}-\left(2 /\left\|\mathbf{z}_{\xi}^{(n)}\right\|^{2}\right)\left(\mathbf{z}_{\xi}^{(n)} \mathbf{z}_{\xi}^{(n) \dagger}\right)$, with $\mathbf{z}_{\xi}^{(n)}=e^{i \phi^{(n)}} \mathbf{x}_{\xi}^{(0)}-\left(\left\|\mathbf{x}_{\xi}^{(0)}\right\| /\left\|\mathbf{x}_{\xi}^{(n)}\right\|\right) \mathbf{x}_{\xi}^{(n)}$. In particular, we have in that case $Q_{\xi \xi}^{(0)}=\mathbb{1}_{\xi}$ and $Q_{\xi \xi}^{(-n)}=Q_{\xi \xi}^{(n) *}$.
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32. More precisely, provided $\sum_{m_{2}} \sum_{m \in M_{0}}\left|\left(\mathcal{W}_{\xi \xi}^{(n, m)}\right)_{m_{1}, m_{2}}\right| \ll 1 / \sqrt{\operatorname{dim} \mathbf{x}_{\xi}}, \forall n \neq 0$, $\forall m_{1}$. This holds in particular if $\operatorname{dim} \mathbf{x}_{\xi}^{3 / 2} \sum_{j}\left|\Omega_{j}\right| / \min \left(\omega_{c}, \Gamma\right) \ll 1$.
33. Indeed, Eq. (22) can be expressed as a function of $\mathbf{x}_{\xi}^{(0)}$ according to $\left(\mathbb{1}+W_{0}\right) \mathbf{y}_{0}=-W_{0}^{\prime} \mathbf{x}_{\xi}^{(0)}$, where $\mathbf{y}_{0}$ is the $\mathbf{y}$ vector excluding the $\mathbf{x}_{\xi}^{(0)}$ component, $W_{0}$ is the $W$ matrix excluding the $W_{\xi \xi}^{\left(0, \prime^{\prime}\right)}$ and $W_{\xi \xi}^{(n, 0)}$ blocks, $\forall n, n^{\prime}$, and $W_{0}^{\prime}$ is the $W$ matrix restricted to the only blocks $W_{\xi \xi}^{(n, 0)}, \forall n \neq 0$. Under condition stated in [32], we have $\left(\mathbb{1}+W_{0}\right)^{-1} \simeq \mathbb{1}+\sum_{k=1}^{+\infty}\left(-W_{0}\right)^{k}$. This implies $\mathbf{y}_{0} \simeq-W_{0}^{\prime} \mathbf{x}_{\xi}^{(0)}$, so that $\left\|\mathbf{x}_{\xi}^{(n)}\right\| \ll\left\|\mathbf{x}_{\xi}^{(0)}\right\|$, and thus $Q_{\xi \xi}^{(n)} \simeq 0_{\xi \xi}, \forall n \neq 0$, i.e., $s_{\xi \xi, j} \simeq \tilde{s}_{\xi \xi, j}$.
34. Indeed, we have $f_{\xi \xi}(\boldsymbol{s}, \boldsymbol{\epsilon}, \delta)=f_{\xi \xi}(S, \boldsymbol{\epsilon}, 0)-(2 \delta s / \Gamma) I_{\xi \xi}(\boldsymbol{\epsilon})$ with $I_{\xi \xi}(\boldsymbol{\epsilon})=$ $\operatorname{Im}\left[\sum_{q, q^{\prime}} \epsilon_{q} \epsilon_{q^{\prime}}^{*}\left(C_{\xi \xi}\right)_{q^{\prime}}^{q}\right]$. Since, for all invertible matrices $A$ and $A-B$, we have $(A-B)^{-1}=A^{-1}+(A-B)^{-1} B A^{-1}$, we get $X_{\xi \xi}(s, \epsilon, \delta)^{-1}=$ $X_{\xi \xi}(s, \epsilon, 0)^{-1}+(2 \delta s / \Gamma) X_{\xi \xi}(s, \epsilon, \delta)^{-1} I_{\xi \xi}(\epsilon) X_{\xi \xi}(s, \epsilon, 0)^{-1}$, $\quad$ where we set $X_{\xi \xi}(\boldsymbol{s}, \boldsymbol{\epsilon}, \delta) \equiv A_{\xi \xi}+f_{\xi \xi}(s, \boldsymbol{\epsilon}, \delta)$. It follows that $\bar{R}(s, \boldsymbol{\epsilon}, \delta)=$ $\bar{R}(s, \boldsymbol{\epsilon}, 0)-2 \delta s N_{J}^{-1} \mathbf{u}_{\xi}^{T} A_{\xi \xi} X_{\xi \xi}(s, \boldsymbol{\epsilon}, \delta)^{-1} \mathbf{u}_{\xi}^{\prime}(s, \boldsymbol{\epsilon}), \quad$ where $\quad \mathbf{u}_{\xi}^{\prime}(s, \boldsymbol{\epsilon}) \equiv$ $I_{\xi \xi}(\epsilon) X_{\xi \xi}(s, \boldsymbol{\epsilon}, 0)^{-1} A_{\xi \xi} \mathbf{u}_{\xi}$. The graph of $\left\|\mathbf{u}_{\xi}^{\prime}(\boldsymbol{s}, \boldsymbol{\epsilon})\right\|^{2}$ as a function of the most general polarization configuration $\epsilon=\cos (\theta / 2) \sigma^{+}+$ $e^{i \varphi} \sin (\theta / 2) \boldsymbol{\sigma}^{-}(\theta \in[0, \pi], \varphi \in[0,2 \pi[)$ always identifies to 0 , whatever $s$ and the atomic structure $\left(J_{g}, J_{e}\right)$, so that $\bar{R}(s, \boldsymbol{\epsilon}, \delta)=\bar{R}(s, \boldsymbol{\epsilon}, 0)$.
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